ORTHOGONAL MATRICES AND THE TRANSPOSE

1. Pythagorean Theorem and Cauchy Inequality

We wish to generalize certain geometric facts from \mathbb{R}^2 to \mathbb{R}^n .

Theorem 1.1. (Pythagorean Theorem) Given two vectors $\vec{x}, \vec{y} \in \mathbb{R}^n$ we have $||\vec{x} + \vec{y}||^2 = ||\vec{x}||^2 + ||\vec{y}||^2 \iff \vec{x} \cdot \vec{y} = 0.$

Proof. One computes

$$\begin{aligned} ||\vec{x} + \vec{y}||^2 &= (\vec{x} + \vec{y}) \cdot (\vec{x} + \vec{y}) = ||\vec{x}||^2 + 2\vec{x} \cdot \vec{y} + ||\vec{y}||^2. \\ \text{Hence, } ||\vec{x} + \vec{y}||^2 &= ||\vec{x}||^2 + ||\vec{y}||^2 \iff \vec{x} \cdot \vec{y} = 0. \end{aligned}$$

A consequence, of this is that for any subspace, $V \subset \mathbb{R}^n$, $||\operatorname{proj}_V(\vec{x})|| \leq ||\vec{x}||$. To see this, note that $\vec{x} = \operatorname{proj}_V(\vec{x}) + \vec{x}^{\perp}$ and two terms are orthogonal. Hence, by the Pythagorean theorem

$$||\vec{x}||^2 = ||\text{proj}_V(\vec{x})||^2 + ||\vec{x}^{\perp}||^2 \ge ||\text{proj}_V(\vec{x})||^2$$

Theorem 1.2. (Cauchy-Schwarz Inequality) If $\vec{x}, \vec{y} \in \mathbb{R}^n$, then $|\vec{x} \cdot \vec{y}| \leq ||\vec{x}|| ||\vec{y}||$.

Proof. Suppose $\vec{y} \neq 0$ (its trivial otherwise). Let $\vec{u} = \frac{1}{||\vec{y}||}\vec{y}$. If $V = \operatorname{span}(\vec{y}) = \operatorname{span}(\vec{u})$, then

$$\operatorname{proj}_{V}(\vec{x}) = ||(\vec{x} \cdot \vec{u})\vec{u}|| = |\vec{x} \cdot \vec{u}| = \frac{|\vec{x} \cdot \vec{y}|}{||\vec{y}||}.$$

Hence,

$$||\vec{x}|| \ge ||\operatorname{proj}_V(\vec{x})|| = \frac{|\vec{x} \cdot \vec{y}|}{||\vec{y}||}$$

multiplying through completes proof.

Recall, for non-zero $\vec{x}, \vec{y} \in \mathbb{R}^2$ we observed that

$$\vec{x} \cdot \vec{y} = ||\vec{x}|| ||\vec{y}|| \cos \theta$$

where θ was the angle between \vec{x} and \vec{y} . The Cauchy-Schwarz inequality implies we can define the angle, θ , between non-zero $\vec{x}, \vec{y} \in \mathbb{R}^n$ in general to be

$$\theta = \arccos \frac{\vec{x} \cdot \vec{y}}{||\vec{x}|| ||\vec{y}||}.$$

2. Orthogonal Transformations and Matrices

Linear transformations that preserve length are of particular interest. A linear transform $T: \mathbb{R}^n \to \mathbb{R}^n$ is *orthogonal* if for all $\vec{x} \in \mathbb{R}^n$

$$||T(\vec{x})|| = ||\vec{x}||.$$

Likewise, a matrix $U \in \mathbb{R}^{n \times n}$ is orthogonal if U = [T] for T an orthogonal transformation. That is, for all \vec{x} ,

$$||U\vec{x}|| = ||\vec{x}||.$$

EXAMPLE: $R_{\theta} : \mathbb{R}^2 \to \mathbb{R}^2$, rotation counter-clockwise by θ , is orthogonal.

NON-EXAMPLE: If $V \neq \mathbb{R}^n$, then $\operatorname{proj}_V : \mathbb{R}^n \to \mathbb{R}^n$ is not orthogonal. Indeed, $\vec{w} \notin V$ satisfies $||\operatorname{proj}_V(\vec{w})|| < ||\vec{w}||$.

3. PROPERTIES OF ORTHOGONAL TRANSFORMATIONS

Orthogonal transformations are so called as they preserve orthogonality:

Theorem 3.1. If $T : \mathbb{R}^n \to \mathbb{R}^n$ is orthogonal and $\vec{v} \cdot \vec{w} = 0$, then $T(\vec{v}) \cdot T(\vec{w}) = 0$.

The matrices kI_n preserve orthogonality, but are only orthogonal when |k| = 1.

 $||T(\vec{v}) + T(\vec{w})||^2 = ||T(\vec{v} + \vec{w})||^2 = ||\vec{v} + \vec{w}||^2 = ||\vec{v}||^2 + ||\vec{w}||^2 = ||T(\vec{v})||^2 + ||T(\vec{w})||^2$ Hence, the claim follows from the Pythagorean theorem.

We have

- (1) Alinear transform $T : \mathbb{R}^n \to \mathbb{R}^n$ is orthogonal if and only if $T(\vec{e}_1), \ldots, T(\vec{e}_n)$ is an orthonormal basis of \mathbb{R}^n
- (2) Similar, $U \in \mathbb{R}^{n \times n}$ is orthogonal if and only if the columns of U form an orthonormal basis of \mathbb{R}^n .

To see the first claim, note that if T is orthogonal, then by definition $T(\vec{e}_i)$ is unit and the previous result implies $T(\vec{e}_i) \cdot T(\vec{e}_j) = 0$ for $i \neq j$ (as $\vec{e}_i \cdot \vec{e}_j = 0$). Hence, $T(\vec{e}_1), \ldots, T(\vec{e}_n)$ is an orthonormal basis. Conversely, suppose $T(\vec{e}_1), \ldots, T(\vec{e}_n)$ forms an orthonormal basis. Consider $\vec{x} = x_1 \vec{e}_1 + \ldots + x_n \vec{e}_n$ We compute

$$||T(\vec{x})||^{2} = ||x_{1}T(\vec{e}_{1}) + \ldots + x_{n}T(\vec{e}_{n})||^{2} = ||x_{1}T(\vec{e}_{1})||^{2} + \ldots + ||x_{n}T(\vec{e}_{n})||^{2} = ||\vec{x}||^{2}.$$

This completes the proof of Claim (1). The second claim is immediate.

Theorem 3.2. If $A, B \in \mathbb{R}^{n \times n}$ are orthogonal, then so is AB. Moreover, A is invertible and A^{-1} is also orthogonal.

Proof. As A and B are orthogonal, we have for any $\vec{x} \in \mathbb{R}^n$

$$||AB\vec{x}|| = ||A(B\vec{x})|| = ||B\vec{x}|| = ||\vec{x}||.$$

This proves the first claim. For the second claim, note that if $A\vec{z} = \vec{0}$, then

$$||\vec{z}|| = ||A\vec{z}|| = ||\vec{0}|| = 0$$

hence, $\vec{x} = \vec{0}$. In particular, $\ker(A) = \left\{\vec{0}\right\}$ so A is invertible. Furthermore,

$$||A^{-1}\vec{x}|| = ||A(A^{-1}\vec{x})|| = ||\vec{x}||$$

so A^{-1} is orthonormal.

4. Transpose

Consider an $m \times n$ matrix A. The transpose, A^{\top} , of A is the $n \times m$ matrix whose entry in the *i*th row and *j*th column is the entry of A in the *j*th row and *i*th column. Geometrically, A^{\top} is obtained from A by reflecting across the diagonal of A.We say A is symmetric if $A^{\top} = A$ and A is skew-symmetric if $A^{\top} = -A$.

EXAMPLE:

$$\begin{bmatrix} 2 & 1 \\ 1 & 0 \\ 1 & 1 \end{bmatrix}^{\top} = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

We compute for $\vec{v}, \vec{w} \in \mathbb{R}^n$ that

$$\vec{v} \cdot \vec{w} = \vec{v}^\top \vec{w}$$

EXAMPLE:

$$\begin{bmatrix} 1\\2 \end{bmatrix} \cdot \begin{bmatrix} -1\\1 \end{bmatrix} = \begin{bmatrix} 1\\2 \end{bmatrix}^{\top} \begin{bmatrix} -1\\1 \end{bmatrix} = \begin{bmatrix} 1&2 \end{bmatrix} \cdot \begin{bmatrix} -1\\1 \end{bmatrix} = 1(-1) + 2(1) = 1.$$

Theorem 4.1. $A \in \mathbb{R}^{n \times n}$ is orthogonal if and only if $A^{\top}A = I_n$, i.e., $A^{-1} = A^{\top}$. *Proof.* Let

$$A = \begin{bmatrix} \vec{v}_1 & | & \cdots & | & \vec{v}_n \end{bmatrix}.$$

Hence,

$$A^{\top} = \begin{bmatrix} \vec{v}_1^{\top} \\ \vdots \\ \vec{v}_n^{\top} \end{bmatrix}$$

and so

$$A^{\top}A = \begin{bmatrix} \vec{v}_1 \cdot \vec{v}_2 & \cdots & \vec{v}_1 \cdot \vec{v}_n \\ \vdots & \ddots & \vdots \\ \vec{v}_n \cdot \vec{v}_i & \cdots & \vec{v}_n \cdot \vec{v}_n \end{bmatrix}.$$

Clearly, $A^{\top}A = I_n$ if and only if the columns of A are orthonormal.

5. Properties of Transpose

The transpose has has several natural algebraic properties

- (1) $(A+B)^{\top} = A^{\top} + B^{\top}$ for $A, B \in \mathbb{R}^{n \times m}$. (2) $(kA)^{\top} = kA^{\top}$ for $A \in \mathbb{R}^{n \times m}$, $k \in \mathbb{R}$. (3) $(AB)^{\top} = B^{\top}A^{\top}$ for $A \in \mathbb{R}^{n \times p}$, $B \in \mathbb{R}^{p \times m}$. (4) $(A\vec{x}) \cdot \vec{y} = \vec{x} \cdot A^{\top}\vec{y}$ for $A \in \mathbb{R}^{n \times m}$, $\vec{x} \in \mathbb{R}^{m}$, $\vec{y} \in \mathbb{R}^{n}$. (5) $(A^{\top})^{-1} = (A^{-1})^{\top}$ for $A \in \mathbb{R}^{n \times n}$ invertible.

Properties (1) and (2) are straightforward to check. To see property (3), write A and B in terms of of their rows and columns

$$A = \begin{bmatrix} \vec{w}_1^\top \\ \vdots \\ \vec{w}_n^\top \end{bmatrix} \text{ and } B = \begin{bmatrix} \vec{v}_1 & | & \cdots & | & \vec{v}_m \end{bmatrix}$$

Where $\vec{v}_i, \vec{w}_j \in \mathbb{R}^p$. Likewise,

$$A^{\top} = \begin{bmatrix} \vec{w}_1 & | & \cdots & | & \vec{w}_n \end{bmatrix} \text{ and } B^{\top} = \begin{bmatrix} \vec{v}_1^{\top} \\ \vdots \\ \vec{v}_m^{\top} \end{bmatrix}$$
$$AB = \begin{bmatrix} \vec{w}_1^{\top} \vec{v}_1 & \cdots & \vec{w}_1^{\top} \vec{v}_m \\ \vdots & \ddots & \vdots \\ \vec{w}_n^{\top} \vec{v}_1 & \cdots & \vec{w}_n^{\top} \vec{v}_m \end{bmatrix} = \begin{bmatrix} \vec{v}_1 \cdot \vec{w}_1 & \cdots & \vec{v}_m \cdot \vec{w}_1 \\ \vdots & \ddots & \vdots \\ \vec{v}_1 \cdot \vec{w}_1 & \cdots & \vec{v}_m \cdot \vec{w}_n \end{bmatrix}$$
$$B^{\top} A^{\top} = \begin{bmatrix} \vec{v}_1^{\top} \vec{w}_1 & \cdots & \vec{v}_1^{\top} \vec{w}_n \\ \vdots & \ddots & \vdots \\ \vec{v}_m^{\top} \vec{w}_1 & \cdots & \vec{v}_m^{\top} \vec{w}_n \end{bmatrix} = \begin{bmatrix} \vec{v}_1 \cdot \vec{w}_1 & \cdots & \vec{v}_1 \cdot \vec{w}_n \\ \vdots & \ddots & \vdots \\ \vec{v}_m \cdot \vec{w}_1 & \cdots & \vec{v}_m \cdot \vec{w}_n \end{bmatrix}$$

One concludes that $(AB)^{\top} = B^{\top}A^{\top}$. To see Property (4) use

$$(A\vec{x}) \cdot \vec{y} = (A\vec{x})^\top \vec{y} = (\vec{x}^\top A^\top) \vec{y} = \vec{x}^\top (A^\top \vec{y}) = \vec{x} \cdot (A^\top \vec{y})$$

Finally, Property (5) can be seen by noting that, as A is invertible,

$$I_n = AA^{-1} \Rightarrow I_n = I_n^{\top} = (AA^{-1})^{\top} = (A^{-1})^{\top}A^{\top}$$

Hence, $(A^{\top})^{-1} = (A^{-1})^{\top}$.

Theorem 5.1. Consider a $A \in \mathbb{R}^{n \times n}$. The following are equivalent

- (1) A is orthogonal matrix
- (2) The transformation $T(\vec{x}) = A\vec{x}$ is orthogonal (i.e. preserves length)
- (3) The columns of A form a orthonormal basis of \mathbb{R}^n
- (4) $A^{\top}A = I_n$ (5) $A^{-1} = A^{\top}$
- (6) A preserves the dot product, i.e. $A\vec{x} \cdot A\vec{y} = \vec{x} \cdot \vec{y}$

Proof. We've already seen why (1)-(4) are equivalent. (4) \iff (5) is immediate. Finally,

$$A\vec{x} \cdot A\vec{y} = \vec{x}(A^{\top}A)\vec{y}$$

So $(4) \Rightarrow (6)$. Going the other direction,

$$||A\vec{x}||^2 = A\vec{x} \cdot A\vec{x}$$

so $(6) \Rightarrow (1)$.

6. MATRIX OF AN ORTHOGONAL PROJECTION

Recall, if \vec{u}_1 is unit and $V = \operatorname{span}(\vec{u}_1)$, then

$$\operatorname{proj}_{V}(\vec{x}) = (\vec{x} \cdot \vec{u}_{1})\vec{u}_{1} = (\vec{u}^{\top}\vec{x})\vec{u}_{1} = \vec{u}_{1}(\vec{u}_{1}^{\top}\vec{x}) = (\vec{u}_{1}\vec{u}_{1}^{\top})\vec{x}$$

Hence, in this case

$$[\operatorname{proj}_V] = \vec{u}_1 \vec{u}_1^\top \in \mathbb{R}^{n \times n}$$

More generally, if $\vec{u}_1, \ldots, \vec{u}_m$ is an orthonormal basis of $V \subset \mathbb{R}^n$, then we have

$$\operatorname{proj}_{V}(\vec{x}) = (\vec{x} \cdot \vec{u}_{1})\vec{u}_{1} + \dots + (\vec{x} \cdot \vec{u}_{m})\vec{u}_{m} = \begin{bmatrix} \vec{u}_{1} & | & \dots & | & \vec{u}_{m} \end{bmatrix} \begin{bmatrix} \vec{u}_{1}^{\top} \\ \vdots \\ \vec{u}_{m}^{\top} \end{bmatrix} \vec{x}$$

That is if

$$Q = \begin{bmatrix} \vec{u}_1 & | & \cdots & | & \vec{u}_m \end{bmatrix},$$

then $\operatorname{proj}_V(\vec{x}) = QQ^{\top}\vec{x}$ Hence,

$$[\operatorname{proj}_V] = QQ^{\top}.$$

EXAMPLE: Let

$$\vec{u}_1 = \frac{1}{2} \begin{bmatrix} 1\\1\\1\\-1 \end{bmatrix}, \vec{u}_2 = \frac{1}{2} \begin{bmatrix} -1\\1\\1\\1 \end{bmatrix}$$

be an orthonormal basis of $V \subset \mathbb{R}^4.$ Clearly,

$$P = [\operatorname{proj}_V] = \frac{1}{4} \begin{bmatrix} 1 & -1 \\ 1 & 1 \\ 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 & -1 \\ -1 & 1 & 1 & 1 \end{bmatrix} = \frac{1}{4} \begin{bmatrix} 2 & 0 & 0 & -2 \\ 0 & 2 & 2 & 0 \\ 0 & 2 & 2 & 0 \\ -2 & 0 & 0 & 2 \end{bmatrix}.$$