

GRAM-SCHMIDT ALGORITHM AND QR FACTORIZATION

1. MOTIVATING PROBLEM

In many situations we have a basis of a subspace, V , but want to find an orthonormal basis. This is useful, for example, in giving a formula for proj_V . The *Gram-Schmidt* algorithm allows us to convert any basis of V to an orthonormal basis. Strategy (for two dimensional V):

- (1) Scale first vector to make it unit.
- (2) Project second vector onto orthogonal complement of first to make it orthogonal to first.
- (3) Scale second vector to make it unit.

EXAMPLE: Find an orthonormal basis of $V = \text{span} \left(\begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 2 \end{bmatrix} \right)$. First, set

$$\vec{u}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{3} \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 2/3 \\ 2/3 \\ 1/3 \end{bmatrix}.$$

Next, project onto orthogonal space to \vec{u}_1

$$\vec{v}_2^\perp = \vec{v}_2 - \vec{v}_2^\parallel = \vec{v}_2 - (\vec{v}_2 \cdot \vec{u}_1) \vec{u}_1 = \begin{bmatrix} 2 \\ 0 \\ 2 \end{bmatrix} - 2 \begin{bmatrix} 2/3 \\ 2/3 \\ 1/3 \end{bmatrix} = \begin{bmatrix} 2/3 \\ -4/3 \\ 4/3 \end{bmatrix}.$$

Finally, normalize the length of this vector:

$$\vec{u}_2 = \frac{1}{\|\vec{v}_2^\perp\|} \vec{v}_2^\perp = \frac{1}{2} \begin{bmatrix} 2/3 \\ -4/3 \\ 4/3 \end{bmatrix} = \begin{bmatrix} 1/3 \\ -2/3 \\ 2/3 \end{bmatrix}$$

So \vec{u}_1, \vec{u}_2 is an orthonormal basis of V . Observe that

$$\vec{v}_1 = 3\vec{u}_1 \text{ and } \vec{v}_2 = 2\vec{u}_1 + 2\vec{u}_2$$

That is,

$$S_{\mathcal{B} \rightarrow \mathcal{U}} = \begin{bmatrix} 3 & 2 \\ 0 & 2 \end{bmatrix}$$

where

$$\mathcal{B} = (\vec{v}_1, \vec{v}_2) \text{ and } \mathcal{U} = (\vec{u}_1, \vec{u}_2)$$

In other words,

$$[\vec{v}_1 \mid \vec{v}_2] = [\vec{u}_1 \mid \vec{u}_2] \begin{bmatrix} 3 & 2 \\ 0 & 2 \end{bmatrix}.$$

2. GRAM-SCHMIDT ALGORITHM

We generalize the above procedure so that it holds any basis. Key Idea: Turn a basis $\mathcal{B} = (\vec{v}_1, \dots, \vec{v}_m)$ of $V \subset \mathbb{R}^n$ into an orthonormal basis $\mathcal{U} = (\vec{u}_1, \dots, \vec{u}_m)$ of V . In order to write this most compactly, we observe that when $V = \{\vec{0}\}$, then for any \vec{x} ,

$$\text{proj}_V(\vec{x}) = \vec{0}.$$

The algorithm is:

- (1) Start $i = 1$
- (2) (Project) Let

$$\vec{v}_i^\perp := \vec{v}_i - \text{proj}_{V_i}(\vec{v}_i) = \vec{v}_i - \sum_{j=1}^{i-1} (\vec{u}_j \cdot \vec{v}_i) \vec{u}_j$$

where $V_i = \text{span}(\vec{v}_1, \dots, \vec{v}_{i-1}) = \text{span}(\vec{u}_1, \dots, \vec{u}_{i-1})$.

- (3) (Scale) Let $\vec{u}_i = \frac{1}{\|\vec{v}_i^\perp\|} \vec{v}_i^\perp$

- (4) If $i < m$, then increment i and start again at (2). Otherwise, we are done.

In the above, by construction, $V_1 = \{\vec{0}\}$ so the first projection does nothing.

Some comments:

- (1) One is constructing the orthonormal basis, $\vec{u}_1, \dots, \vec{u}_{i-1}$, of V_i from the previous steps in the algorithm. This means one can compute the orthogonal projection in a straightforward manner.
- (2) The fact that \mathcal{B} is a basis is what ensures that $\|\vec{v}_i^\perp\| > 0$.

EXAMPLE: Compute an orthonormal basis of

$$\ker \begin{bmatrix} 1 & 3 & 0 & -2 \\ 0 & 0 & 1 & 2 \end{bmatrix}.$$

This matrix is in rref already so we have

$$\ker = \text{span} \left(\begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix} \right)$$

Lets take a basis to be

$$\vec{v}_1 = \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix} \text{ and } \vec{v}_2 = \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

We apply the Gram-Schmidt algorithm to this to obtain:

$$\vec{u}_1 = \frac{1}{3} \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

and

$$\vec{v}_2^\perp = \vec{v}_2 - (\vec{v}_2 \cdot \vec{u}_1) \vec{u}_1 = \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + \frac{1}{3} \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix} = \frac{2}{3} \begin{bmatrix} -5 \\ 3 \\ -4 \\ 2 \end{bmatrix}$$

and

$$\|\vec{v}_2^\perp\| = \frac{2}{3}\sqrt{(-5)^2 + 3^2 + (-4)^2 + 2^2} = \frac{2}{3}\sqrt{54} = 2\sqrt{6}.$$

Hence,

$$\vec{u}_2 = \frac{1}{3\sqrt{6}} \begin{bmatrix} -5 \\ 3 \\ -4 \\ 2 \end{bmatrix} = \frac{\sqrt{6}}{18} \begin{bmatrix} -5 \\ 3 \\ -4 \\ 2 \end{bmatrix}.$$

3. QR FACTORIZATION

Let $\mathcal{B} = (\vec{v}_1, \dots, \vec{v}_m)$ be a basis of $V \subset \mathbb{R}^n$. Suppose that $\mathcal{U} = (\vec{u}_1, \dots, \vec{u}_m)$ is the basis obtained from \mathcal{B} by the Gram-Schmidt algorithm. If we write

$$R = S_{\mathcal{B} \rightarrow \mathcal{U}}, M = [\vec{v}_1 \mid \cdots \mid \vec{v}_m] \text{ and } Q = [\vec{u}_1 \mid \cdots \mid \vec{u}_m],$$

then we have

$$M = QR$$

If one looks at how the Gram-Schmidt algorithm works, it is not hard to see that R is upper triangular and the diagonal elements are all positive. Such a factorization is called a QR -factorization and is useful in many computational settings. Notice, that by definition, if M has a QR -factorization $M = QR$, then the columns of Q form an orthonormal basis of $\text{Im}(M)$.

EXAMPLE: Compute the QR factorization of

$$M = \begin{bmatrix} 2 & 0 \\ 1 & 6 \\ -2 & -6 \end{bmatrix}$$

Have

$$\vec{v}_1 = \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix} \text{ and } \vec{v}_2 = \begin{bmatrix} 0 \\ 6 \\ -6 \end{bmatrix}.$$

As such,

$$\vec{u}_1 = \frac{1}{3}\vec{v}_1 = \begin{bmatrix} 2/3 \\ 1/3 \\ -2/3 \end{bmatrix}$$

and

$$\vec{v}_2^\perp = \vec{v}_2 - (\vec{v}_2 \cdot \vec{u}_1)\vec{u}_1 = \begin{bmatrix} 0 \\ 6 \\ -6 \end{bmatrix} - 6 \begin{bmatrix} 2/3 \\ 1/3 \\ -2/3 \end{bmatrix} = \begin{bmatrix} -4 \\ 4 \\ -2 \end{bmatrix}$$

and

$$\vec{u}_2 = \frac{1}{6} \begin{bmatrix} -4 \\ 4 \\ -2 \end{bmatrix} = \begin{bmatrix} -2/3 \\ 2/3 \\ -1/3 \end{bmatrix}.$$

Clearly, $\vec{v}_1 = 3\vec{u}_1$ and $\vec{v}_2 = 6\vec{u}_1 + 6\vec{u}_2$ and so

$$\underbrace{\begin{bmatrix} 2 & 0 \\ 1 & 6 \\ -2 & -6 \end{bmatrix}}_M = \underbrace{\begin{bmatrix} 2/3 & -2/3 \\ 1/3 & 2/3 \\ -2/3 & -1/3 \end{bmatrix}}_Q \underbrace{\begin{bmatrix} 3 & 6 \\ 0 & 6 \end{bmatrix}}_R$$