

Johns Hopkins University
 Math 201, Spring 2007
 Name:
 Section:

Midterm Exam # 2

Time: 50 minutes

No books, notes, calculators. Please explain carefully all steps leading to your solutions, or risk losing credit.

Problem 1: (6 points = 2+1+1+2) Consider the plane E in \mathbb{R}^3 with equation $x_1 + 2x_2 + x_3 = 0$, and let p denote the orthogonal projection onto E .

1. If (u_1, u_2) is an orthonormal basis of E , write the formula for $p(v)$ in terms of u_1 and u_2 (where v is any vector in \mathbb{R}^3).
2. Find a basis of E .
3. Find an orthonormal basis of E .
4. Find the matrix for p in the standard basis of \mathbb{R}^3 .

1) $p(v) = (v \cdot u_1)u_1 + (v \cdot u_2)u_2$

2) Take any two vectors in E which are not proportional, such as: $v_1 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, v_2 = \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix}$

3) We find an orthonormal basis of E by applying the Gram-Schmidt procedure to (v_1, v_2) . This gives:

$$u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, v_2^\perp = v_2 - (v_2 \cdot u_1)u_1 = \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} - \frac{2}{\sqrt{2}} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}, u_2 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

(u_1, u_2) is then an orthonormal basis of E .

4) We use questions 1) and 3) to find $p(e_1), p(e_2), p(e_3)$ where $e_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, e_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, e_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ are the vectors of the standard basis in \mathbb{R}^3 :

$$p(e_1) = \frac{1}{\sqrt{2}} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + \frac{1}{\sqrt{3}} \cdot \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 5/6 \\ -1/3 \\ -1/6 \end{pmatrix}, p(e_2) = 0 - \frac{1}{\sqrt{3}} \cdot \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1/3 \\ 1/3 \\ -1/3 \end{pmatrix}$$

$$p(e_3) = -\frac{1}{\sqrt{2}} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + \frac{1}{\sqrt{3}} \cdot \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} -1/6 \\ -1/3 \\ 5/6 \end{pmatrix}. \quad \text{The matrix for } p \text{ in the basis } (e_1, e_2, e_3) \text{ is therefore:}$$

$$\begin{pmatrix} 5/6 & 1/3 & -1/6 \\ -1/3 & 1/3 & -1/3 \\ -1/6 & -1/3 & 5/6 \end{pmatrix}$$

Problem 2: (9 points=3+2+1+1+2) Consider the linear space P of polynomials with real coefficients.

- Are the following subsets of P linear subspaces? Explain why.

- the set E_0 of polynomials p such that $p(0) = 0$
- the set E_1 of polynomials p such that $p(1) = 1$
- the set P_2 of polynomials of degree 2 or less

Consider the linear map f from P_2 to P_2 defined by $f(p(x)) = p''(x) + 3p'(x)$.

- Find the kernel of f . Is f an isomorphism?
- Find the matrix for f in the standard basis $(1, x, x^2)$ of P_2 .
- Prove that the vectors $p_1 = 2 + x$, $p_2 = 3$, $p_3 = 1 + 2x + 3x^2$ are linearly independant.
- Find the matrix for f in the basis (p_1, p_2, p_3) .

1) $\star E_0$ is a linear subspace of P :

- the 0 polynomial is in E_0 .
- E_0 is closed under addition and scalar multiplication

(if $p_1, p_2 \in E_0$, then $(p_1 + p_2)(0) = p_1(0) + p_2(0) = 0$; if $\lambda \in \mathbb{R}$, $\lambda p_1(0) = \lambda \cdot 0 = 0$)

$\star E_1$ is not a linear subspace of P : each condition fails.

the 0 polynomial is not in E_1 , E_1 is not closed under addition or scalar multiplication

$\star P_2$ is a linear subspace of P (seen in class and in the book): contains 0, closed under addition and scalar multiplication

2) Let $p(x) = ax^2 + bx + c$ be in P_2 . Then: $p'(x) = 2ax + b$, $p''(x) = 2a$

Thus: $f(p(x)) = 0 \Leftrightarrow 2a + 3(2ax + b) = 0$ (for all x) $\Leftrightarrow a = 0$ and $b = 0$

Therefore: $\text{Ker } f = \{\text{constant polynomials}\} = \text{Span}(1)$. f is not an isomorphism.

3) We find the image of the basis vectors:

$$f(1) = 0 = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \quad f(x) = 3 = \begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix}, \quad f(x^2) = (x+2) = \begin{pmatrix} 2 \\ 6 \\ 0 \end{pmatrix}$$

so the matrix for f in $(1, x, x^2)$ is: $\begin{pmatrix} 0 & 3 & 2 \\ 0 & 0 & 6 \\ 0 & 0 & 0 \end{pmatrix}$

4) These vectors are linearly independent because they have different degrees. More explicitly, if $c_1p_1 + c_2p_2 + c_3p_3 = 0$:

$$c_1(2+x) + 3c_2 + c_3(1+2x+3x^2) = 0 \text{ for all } x$$

$$2c_1 + 3c_2 + c_3 + (c_1 + 2c_2)x + 3c_3x^2 = 0 \text{ for all } x$$

↓

$$2c_1 + 3c_2 + c_3 = 0 \text{ and } c_1 + 2c_2 = 0 \text{ and } 3c_3 = 0$$

↓

$c_1 = c_2 = c_3 = 0$. Therefore the 3 vectors are linearly independent.

5) We find the images $f(p_1), f(p_2), f(p_3)$ and write them in terms of p_1, p_2, p_3 (so we write the matrix column by column).

$$f(p_1) = 3 = p_2, \quad f(p_2) = 0, \quad f(p_3) = (8x+12) = 18(x+2) - 24 = 18p_1 - 8p_2$$

so the matrix for f in (p_1, p_2, p_3) is $\begin{pmatrix} 0 & 0 & 18 \\ 1 & 0 & -8 \\ 0 & 0 & 0 \end{pmatrix}$

Problem 3: (5 points=1+2+2)

Consider the matrix:

$$M = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 1 & 2 & 1 \end{pmatrix}$$

and let v_1, v_2, v_3 denote its column vectors.

1. Prove that v_1, v_2, v_3 are linearly independent.
2. Perform the Gram-Schmidt process on (v_1, v_2, v_3) .
3. Write the QR-factorization of M .

1) If v_3 was a linear combination $c_1v_1 + c_2v_2$, then we would have:
 $c_1 = 1, c_2 = -1$, and $c_1 + 2c_2 = 1$ which is impossible.

2) $u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$

$$u_2 = \frac{v_2^\perp}{\|v_2^\perp\|}, \quad v_2^\perp = v_2 - (v_2 \cdot u_1)u_1 = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} - \frac{2}{\sqrt{2}} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}$$

$$u_2 = \frac{1}{\sqrt{3}} \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}$$

$$\begin{aligned} u_3 &= \frac{v_3^\perp}{\|v_3^\perp\|}, \quad v_3^\perp = v_3 - (v_3 \cdot u_1)u_1 - (v_3 \cdot u_2)u_2 \\ &= \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} - \frac{1}{\sqrt{2}} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} - \frac{1}{\sqrt{3}} \cdot \frac{1}{\sqrt{3}} \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -1/3 \\ -2/3 \\ 1/3 \end{pmatrix} \end{aligned}$$

$$u_3 = \frac{1}{\sqrt{6}} \begin{pmatrix} -1 \\ -2 \\ 1 \end{pmatrix}$$

3) Thus $M = QR$, with $Q = \begin{pmatrix} u_1 & u_2 & u_3 \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{6}} \\ 0 & \frac{1}{\sqrt{3}} & -\frac{2}{\sqrt{6}} \end{pmatrix}$

$$\text{and } R = \begin{pmatrix} \|v_1\| & v_1 \cdot u_1 & v_3 \cdot u_1 \\ 0 & \|v_2\| & v_3 \cdot u_2 \\ 0 & 0 & \|v_3\| \end{pmatrix} = \begin{pmatrix} \sqrt{2} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{6}} \\ 0 & \sqrt{2} & \sqrt{2} \\ 0 & 0 & \frac{\sqrt{6}}{3} \end{pmatrix}$$