Fall 2012 110.107 Calc II Exam 1

October 15, 2012

1. [10 pts]

Let $A = \begin{bmatrix} -1 & 0 & 3 \\ 1 & -2 & 1 \end{bmatrix} B = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$ and $C = \begin{bmatrix} 2 & 1 & 0 \\ 0 & -3 & -1 \end{bmatrix}$. Decide which of the following operations are well defined, and carry out

those, which are defined. If not defined, briefly explain the reason.

a)
$$B(C-2A)$$

$$B(C-2A) = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \left(\begin{bmatrix} 2 & 1 & 0 \\ 0 & -3 & -1 \end{bmatrix} - 2 \begin{bmatrix} -1 & 0 & 3 \\ 1 & -2 & 1 \end{bmatrix} \right)$$
$$= \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \left(\begin{bmatrix} 2 & 1 & 0 \\ 0 & -3 & -1 \end{bmatrix} - \begin{bmatrix} 2(-1) & 2(0) & 2(3) \\ 2(1) & 2(-2) & 2(1) \end{bmatrix} \right)$$
$$= \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \left(\begin{bmatrix} 2 & 1 & 0 \\ 0 & -3 & -1 \end{bmatrix} - \begin{bmatrix} -2 & 0 & 6 \\ 2 & -4 & 2 \end{bmatrix} \right)$$
$$= \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 - (-2) & 1 - 0 & 0 - 6 \\ 0 - 2 & -3 - (-4) & -1 - 2 \end{bmatrix}$$
$$= \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 4 & 1 & -6 \\ -2 & 1 & -3 \end{bmatrix}$$
$$= \begin{bmatrix} 1(4) + (-1)(-2) & 1(1) + (-1)(1) & 1(-6) + (-1)(-3) \\ 0(4) + 1(-2) & 0(1) + 1(1) & 0(-6) + 1(-3) \end{bmatrix}$$
$$= \begin{bmatrix} 6 & 0 & -3 \\ -2 & 1 & -3 \end{bmatrix}$$

b) C(A+B)'

A+B would be $\begin{bmatrix} -1 & 0 & 3 \\ 1 & -2 & 1 \end{bmatrix} + \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$, which is the sum of two matrices with different dimensions. Thus, the operation A+B is not defined. Since it's not defined, we certainly can't take the transpose of it and then left-multiply by C, so the whole expression is not defined.

2. [15 pts]

Consider the following system of linear equations

$$x - y + 2z = 2$$
$$x + 2y - z = 5$$
$$y - z = 1$$

a) Write the augmented matrix of the system.

[1	-1	2	2
	1	2	-1	5
	0	1	-1	1

b) Find the solution set of the system.

Subtracting the first row from the second (and writing in the second row) yields: $\begin{bmatrix} 1 & -1 & 2 & | & 2 \\ 0 & 3 & -3 & | & 3 \\ 0 & 1 & -1 & | & 1 \end{bmatrix}$. Subtracting three times the third row from the second

(and writing in the third row) yields $\begin{bmatrix} 1 & -1 & 2 & 2 \\ 0 & 3 & -3 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$. Now that the system

in upper-triangular form, we can see that it is underdetermined. We may let z be an arbitrary parameter t. The second row represents 3y - 3z = 3, so y = z + 1 = t + 1. Finally, the first equation represents

$$x - y + 2z = 2$$
, so $x - (t + 1) + 2t = 2$, and

$$x - t - 1 + 2t = 2$$
 so that $x + t - 1 = 2$ and $x = 3 - t$.

Thus, the solution set is $[(3-t,t+1,t):t \in \mathbb{R}]$. Note: There are many other valid ways of writing the solution set.

2. [20 pts]

Each of the two definite integral below is improper. Choose ONLY ONE of them. For this choice, either show that the integral does not exist, or calculate its value.

$$\int_{-1}^{1} \frac{1}{\sqrt[3]{x+1}} \mathrm{d}x$$

First, note that while the bounds of integration are finite, the integrand is undefined at -1 (due to division by zero). Therefore, we need to write the integral as a limit:

$$\lim_{a \to -1^+} \int_a^1 \frac{1}{\sqrt[3]{x+1}} \mathrm{d}x$$

We then substitute u = x + 1, du = dx. So that we don't have to worry about converting things back in terms of x at the end, we change the bounds of integration now: If x = a, then u = a + 1, and if x = 1, then u = 1 + 1 = 2, so the integral becomes:

$$\lim_{a \to -1^+} \int_{a+1}^2 \frac{1}{\sqrt[3]{u}} du = \lim_{a \to -1^+} \int_{a+1}^2 u^{-1/3} du$$
$$= \lim_{a \to -1^+} \left(\frac{3}{2} u^{2/3} \Big|_{a+1}^2 \right) = \lim_{a \to -1^+} \left(\frac{3}{2} * 2^{2/3} - \frac{3}{2} (a+1)^{2/3} \right)$$
$$= \frac{3}{2} * 2^{2/3} - \frac{3}{2} (-1+1)^{2/3} \text{ since } f(x) = (x+1)^{2/3} \text{ is continuous everywhere}$$
$$= \boxed{\frac{3}{2} * \sqrt[3]{4}}.$$

b)

$$\int_2^\infty \frac{x}{\left(x^2 - 1\right)^2} \mathrm{d}x$$

First, note that the integrand is defined everywhere except $x = \pm 1$, so that the only limit we have to worry about is the one for the infinite bound of integration:

$$\lim_{b \to \infty} \int_2^b \frac{x}{\left(x^2 - 1\right)^2} \mathrm{d}x.$$

We then substitute $u = x^2 - 1$, du = 2xdx, so (1/2) du = xdx. So that we don't have to worry about converting things back in terms of x at the end, we change the bounds of integration now: If x = 2, then $u = 2^2 - 1 = 3$, and if x = b, then $u = b^2 - 1$, so the integral becomes:

$$\lim_{b \to \infty} \int_{3}^{b^{2}-1} \frac{(1/2) \, \mathrm{d}u}{u^{2}} = \lim_{b \to \infty} \frac{1}{2} \int_{3}^{b^{2}-1} \frac{\mathrm{d}u}{u^{2}}$$
$$= \lim_{b \to \infty} \frac{1}{2} \int_{3}^{b^{2}-1} u^{-2} \mathrm{d}u = \lim_{b \to \infty} \frac{1}{2} \left(-u^{-1} \Big|_{3}^{b^{2}-1} \right)$$

a)

$$= \lim_{b \to \infty} \frac{1}{2} \left(-\frac{1}{b^2 - 1} - \left(-\frac{1}{3} \right) \right) = \frac{1}{6} - \lim_{b \to \infty} \frac{1}{2(b^2 - 1)} = \boxed{\frac{1}{6}}$$

with the final step following from the fact that $2(b^2 - 1)$ grows without bound as b does, so that the limit of the whole fraction is zero.

4. [20 pts]

Solve the following first order separable initial value problem for $x \ge 0$ given by

$$\frac{\mathrm{d}y}{\mathrm{d}x} = e^{-y} \left(2 + \cos(x)\right) \text{ and } y(0) = 0.$$

We have $\frac{\mathrm{d}y}{e^{-y}} = (2 + \cos(x)) \,\mathrm{d}x$ (this division is ok since e^{-y} is never 0)

$$\Rightarrow \int \frac{\mathrm{d}y}{e^{-y}} = \int \left(2 + \cos\left(x\right)\right) \mathrm{d}x \Rightarrow \int e^y \mathrm{d}y = \int \left(2 + \cos\left(x\right)\right) \mathrm{d}x$$
$$\Rightarrow e^y = 2x + \sin x + C$$

 $\Rightarrow y = \ln (2x + \sin x + C)$ is the general solution

Now we must use the initial value, plugging in 0 for y and 0 for x since y(0) = 0:

 $0 = \ln (2(0) + \sin 0 + C) = \ln (C)$, so C = 1

Thus, the particular solution to this initial value problem is

$$y = \ln\left(2x + \sin x + 1\right)$$

5. [10 pts]

Consider the line in the plane passing through the point (-1, 2) and perpendicular to the vector $\vec{n} = \begin{bmatrix} 3\\4 \end{bmatrix}$.

a) Find an equation for the line.

Reading off the numerical data, one equation is 3(x - (-1)) + 4(y - 2) = 0, i.e. 3(x + 1) + 4(y - 2) = 0 or 3x + 4y - 5 = 0. The first equation can come from a memorized formula from your textbook.

However, if you didn't memorize that, note that $\begin{bmatrix} x - (-1) \\ y - 2 \end{bmatrix}$ is the vector (in the direction of the line) from the point (-1, 2) to an arbitrary point on the line (x, y). Then since the line is perpendicular to $\begin{bmatrix} 3 \\ 4 \end{bmatrix}$, we have $\begin{bmatrix} 3 \\ 4 \end{bmatrix} \bullet \begin{bmatrix} x - (-1) \\ y - 2 \end{bmatrix} = 0$, so $3(x - (-1)) + 4(y - 2) = 0\checkmark$

b) Find a parametric equation for the line.

Now that we have an equation, we can let almost any expression be our parameter; let's take x = t for simplicity. Then 3t + 4y - 5 = 0 so y = (5 - 3t)/4.

x = t and y = (5 - 3t)/4 is one way to write the answer.

6. [25 pts]

Let $A = \begin{bmatrix} x & y \\ y & x \end{bmatrix}$ and assume that $A \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 5 \\ 2 \end{bmatrix}$

a) Find x and y.

$$A\begin{bmatrix}3\\4\end{bmatrix} = \begin{bmatrix}5\\2\end{bmatrix} \Rightarrow \begin{bmatrix}x&y\\y&x\end{bmatrix} \begin{bmatrix}3\\4\end{bmatrix} = \begin{bmatrix}5\\2\end{bmatrix}$$
$$\Rightarrow \begin{bmatrix}x*3+y*4\\y*3+x*4\end{bmatrix} = \begin{bmatrix}5\\2\end{bmatrix}$$
$$\Rightarrow \begin{cases}3x+4y&=5\\4x+3y&=2\end{cases}$$

 $\Rightarrow \begin{cases} x - y &= 2 - 5\\ 4x + 3y &= 2 \end{cases}$ by subtracting the first from the second

$$\Rightarrow \begin{cases} x = y - 3\\ 4x + 3y = 2 \end{cases} \Rightarrow \begin{cases} x = y - 3\\ 4(y - 3) + 3y = 2 \end{cases}$$
$$\Rightarrow \begin{cases} x = y - 3\\ 7y - 12 = 2 \end{cases} \Rightarrow \begin{cases} x = y - 3\\ 7y = 14 \end{cases}$$
$$\Rightarrow \begin{cases} x = y - 3\\ y = 2 \end{cases} \Rightarrow \boxed{\begin{cases} x = -1\\ y = 2 \end{cases}}$$

b) Calculate A^{-1}

From part a), $A = \begin{bmatrix} -1 & 2 \\ 2 & -1 \end{bmatrix}$, so det A = (-1)(-1) - (2)(2) = -3.

$$A^{-1} = \frac{1}{\det A} \begin{bmatrix} A_{22} & -A_{12} \\ -A_{21} & A_{11} \end{bmatrix} = \frac{1}{-3} \begin{bmatrix} -1 & -2 \\ -2 & -1 \end{bmatrix} = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} \end{bmatrix}$$

c) Calculate the eigenvalues and corresponding eigenvectors of A.

First, we must find the eigenvalues, using det $(A - \lambda I) = 0$.

$$A - \lambda I = \begin{bmatrix} -1 & 2\\ 2 & -1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0\\ 0 & 1 \end{bmatrix} = \begin{bmatrix} -1 - \lambda & 2\\ 2 & -1 - \lambda \end{bmatrix}$$

so det $(A - \lambda I) = (-1 - \lambda)^2 - 2^2 = \lambda^2 + 2\lambda + 1 - 4 = (\lambda + 3)(\lambda - 1).$

The eigenvalues, solutions to det $(A - \lambda I) = 0$, are thus $\lambda = -3$ and $\lambda = 1$. Now we must find eigenvectors:

For $\lambda = -3$, an eigenvector $\vec{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ satisfies

$$A\overrightarrow{v} = -3\overrightarrow{v} \text{ so } \begin{bmatrix} -1 & 2\\ 2 & -1 \end{bmatrix} \begin{bmatrix} v_1\\ v_2 \end{bmatrix} = -3\begin{bmatrix} v_1\\ v_2 \end{bmatrix}$$
$$\Rightarrow \begin{bmatrix} -v_1 + 2v_2\\ 2v_1 - v_2 \end{bmatrix} = \begin{bmatrix} -3v_1\\ -3v_2 \end{bmatrix} \Rightarrow \begin{bmatrix} 2v_1 + 2v_2\\ 2v_1 + 2v_2 \end{bmatrix} = \begin{bmatrix} 0\\ 0 \end{bmatrix}$$
$$\Rightarrow v_2 = -v_1.$$

Thus, every eigenvector corresponding to the eigenvalue $\lambda = -3$ has the form $\begin{bmatrix} v_1 \\ -v_1 \end{bmatrix}$ for some nonzero v_1 . However, full credit was given for a particular eigenvector, such as $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$. For $\lambda = 1$, an eigenvector $\vec{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ satisfies $A\vec{v} = 1\vec{v}$ so $\begin{bmatrix} -1 & 2 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = 1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ $\Rightarrow \begin{bmatrix} -v_1 + 2v_2 \\ 2v_1 - v_2 \end{bmatrix} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \Rightarrow \begin{bmatrix} -2v_1 + 2v_2 \\ 2v_1 - 2v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Thus, every eigenvector corresponding to the eigenvalue $\lambda = 1$ has the form $\begin{bmatrix} v_1 \\ v_1 \end{bmatrix}$ for some nonzero v_1 . However, full credit was given for a particular eigenvector, such as $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

 $\Rightarrow v_2 = v_1.$