## FINAL PRACTICE EXAM I (SOLUTION)

## $\rm YI~LI$

1. Determine if the following improper integral converges or diverges. If the integral is convergent compute its value.

$$\int_0^\infty x e^{-x} \, dx.$$

By integration by parts, we have

$$\int_{0}^{\infty} x e^{-x} dx = -\int_{0}^{\infty} x d(e^{-x}) = -\left(x e^{-x}\Big|_{0}^{\infty} - \int_{0}^{\infty} e^{-x} dx\right)$$
$$= -\left(0 - \int_{0}^{\infty} e^{-x} dx\right) = \int_{0}^{\infty} e^{-x} dx$$
$$= -e^{-x}\Big|_{0}^{\infty} = -(0 - 1) = 1.$$

**2.** Let

$$f(x,y) = \begin{cases} \frac{3x^2y^2}{x^3+y^6}, & \text{if } (x,y) \neq (0,0), \\ 0, & \text{if } (x,y) = (0,0). \end{cases}$$

(a) Does the  $\lim_{(x,y)\to(0,0)} f(x,y)$  exist? (b) Is f(x,y) continuous at (0,0)?

(a) For the line  $C_1 : y = mx$ , we have

$$\lim_{(x,y)\to(0,0) \text{ along with } C_1} f(x,y) = \lim_{x\to 0} f(x,mx) = \lim_{x\to 0} \frac{3m^2 x^4}{x^3 + m^6 x^6}$$
$$= \lim_{x\to 0} \frac{3m^2 x}{1 + m^6 x^3} = 0.$$

For the line  $C_2: x = y^2$ , we have

(x,y)

$$\lim_{y \to (0,0) \text{ along with } C_2} f(x,y) = \lim_{y \to 0} f(y^2,y) = \lim_{y \to \infty} \frac{3y^6}{2y^6} = \frac{3}{2}.$$

Hence, the limit  $\lim_{(x,y)\to(0,0)} f(x,y)$  does not exist. (b) By part (a), it immediately follows that f(x,y) is discontinuous at (0,0).

3. Solve the following first order separable initial value problem

$$\frac{dy}{dx} = (y-1)(y-2)$$

with y(0) = 0.

Write the differential equation as

$$\frac{dy}{(y-1)(y-2)} = dx.$$

The rational function 1/(y-1)(y-2) has the following partial fraction:  $1 \qquad A \qquad B$ 

$$\overline{(y-1)(y-2)} = \overline{y-1} + \overline{y-2}$$

for some constants A and B. Since

(y

$$\frac{A}{y-1} + \frac{B}{y-2} = \frac{A(y-2) + B(y-1)}{(y-1)(y-2)} = \frac{(A+B)y - (2A+B)}{(y-1)(y-2)}$$

it follows that

$$A + B = 0, \quad 2A + B = -1$$

Solving the above two linear equations yields A = -1 and B = 1. Hence

$$\frac{1}{(-1)(y-2)} = \frac{-1}{y-1} + \frac{1}{y-2} = \frac{1}{y-2} - \frac{1}{y-1}.$$

Plugging this decomposition into above, we arrive at

$$\left(\frac{1}{y-2} - \frac{1}{y-1}\right)dy = dx \Longrightarrow \ln\left|\frac{y-2}{y-1}\right| = x + C_1$$

for some constant. Thus

$$\frac{y-2}{y-1} = Ce^x \quad (C = \pm e^{C_1}) \Longrightarrow y = \frac{2 - Ce^x}{1 - Ce^x}.$$

Using y(0) = 0, we get  $0 = \frac{2-C}{1-C}$  and then C = 2. Hence

$$y = \frac{2 - 2e^x}{1 - 2e^x}$$

4. Consider the system of linear equations

$$x_1 - x_2 = 0$$
  

$$3x_1 + x_2 - x_3 = 11$$
  

$$2x_1 + x_2 + 2x_3 = 11$$

Find the augmented matrix of the above system and use it to solve the system.

1 -1

The augmented matrix is

Then

0 0

Therefore, z = 1, y = 3, and x = 3.

**5.** Consider  $f(x, y) = 3xy - x^3 - y^3$ .

(a) Locate all critical points of f(x, y).

(b) Classify the critical points of f(x, y) (i.e., determine if they are local maximum/local minimum or saddle point).

(c) Does f have a global maximum or minimum on  $\mathbf{R}^2$ ? Briefly explain!

Since f(x, y) is differentiable at any points of  $\mathbf{R}^2$ , all critical points must satisfy  $\begin{bmatrix} 0 \\ -\nabla f(x, y) \end{bmatrix} = \begin{bmatrix} 3y - 3x^2 \end{bmatrix}$ 

$$\begin{bmatrix} 0\\0 \end{bmatrix} = \nabla f(x,y) = \begin{bmatrix} 3y & 3x\\ 3x - 3y^2 \end{bmatrix}$$

(a) If  $(x_0, y_0)$  is a critical point, then

$$y_0 - x_0^2 = 0$$
,  $x_0 - y_0^2 = 0$ .

Thus  $(x_0, y_0) = (0, 0)$  or (1, 1).

(b) The Hessian matrix of f is

$$\mathbf{Hess}(f)(x,y) = \begin{bmatrix} -6x & 3\\ 3 & -6y \end{bmatrix}$$

For (0,0), its Hessian matrix has the form

$$H = \mathbf{Hess}(f)(0,0) = \begin{bmatrix} 0 & 3\\ 3 & 0 \end{bmatrix}, \quad \det H = -9 < 0;$$

this critical point is a saddle point.

For (1, 1), its Hessian matrix has the form

$$H = \mathbf{Hess}(f)(1,1) = \begin{bmatrix} -6 & 3\\ 3 & -6 \end{bmatrix}, \quad \det H = 27 > 0, \quad \operatorname{tr} H = -12 < 0;$$

the function f(x, y) has a local maximum at this critical point.

(c) Consider a line y = ax. Then

$$f(x,y) = f(x,ax) = 3ax^2 - x^3 - a^3x^3.$$

Choose a = 0, we have

$$f(x,0) = -x^3 \to -\infty$$
 as  $x \to \infty$ 

and

$$f(x,0) = -x^3 \to +\infty$$
 as  $x \to -\infty$ .

This means that f has no global extrema.

6. Consider the following system of differential equations

$$\begin{bmatrix} \frac{dx_1}{dt} \\ \frac{dx_2}{dt} \end{bmatrix} = \begin{bmatrix} -5 & -2 \\ 6 & 3 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

Solve the following initial value problem with  $x_1(0) = 5$  and  $x_2(0) = 3$ .

Let

$$A = \begin{bmatrix} -5 & -2\\ 6 & 3 \end{bmatrix}$$

From det A = -3 and tr A = -2, we get

$$0 = \lambda^2 - \lambda \operatorname{tr} A + \det A = \lambda^2 + 2\lambda - 3 = (\lambda + 3)(\lambda - 1).$$

The two eigenvalues are  $\lambda_1 = 1$  and  $\lambda_2 = -3$ .

If **u** is an eigenvector of  $\lambda_1$ , then  $0 = (A - \lambda_1 I_2)\mathbf{u} = \left( \begin{bmatrix} -5 & -2\\ 6 & 3 \end{bmatrix} - \begin{bmatrix} 1 & 0\\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} u_1\\ u_2 \end{bmatrix} = \begin{bmatrix} -6 & -2\\ 6 & 2 \end{bmatrix} \begin{bmatrix} u_1\\ u_2 \end{bmatrix}$ 

and  $u_2 = -3u_1$ . Hence

$$\mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} u_1 \\ -3u_1 \end{bmatrix} = u_1 \begin{bmatrix} 1 \\ -3 \end{bmatrix}.$$

If **v** is an eigenvector of  $\lambda_2$ , then

$$0 = (A - \lambda_1 I_2)\mathbf{u} = \left( \begin{bmatrix} -5 & -2\\ 6 & 3 \end{bmatrix} + 3 \begin{bmatrix} 1 & 0\\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1\\ v_2 \end{bmatrix} = \begin{bmatrix} -2 & -2\\ 6 & 6 \end{bmatrix} \begin{bmatrix} v_1\\ v_2 \end{bmatrix}$$

and  $v_2 = -v_1$ . Hence

$$\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} v_1 \\ -v_1 \end{bmatrix} = v_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

The general solution now is given by

$$\mathbf{x}(t) = c_1 e^t \begin{bmatrix} 1\\ -3 \end{bmatrix} + c_2 e^{-3t} \begin{bmatrix} 1\\ -1 \end{bmatrix} = \begin{bmatrix} c_1 e^t + c_2 e^{-3t} \\ -3c_1 e^t - c_2 e^{-3t} \end{bmatrix}.$$

From  $x_1(0) = 5$  and  $x_2(0) = 3$ , we find that

$$c_1 + c_2 = 5, \quad -3c_1 - c_2 = 3.$$

Solving those linear equations gives us  $c_1 = -4$  and  $c_2 = 9$ . Consequently

$$\mathbf{x}(t) = \begin{bmatrix} -4e^t + 9e^{-3t} \\ 12e^t - 9e^{-3t} \end{bmatrix}$$

7. Find the absolute maxima and minima of  $f(x, y) = x^2 + y^2 - 2x + 4$  on the disk  $D = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 \le 4\}$ .

Compute

$$abla f(x,y) = \begin{bmatrix} 2x-2\\2y \end{bmatrix}, \quad \mathbf{Hess}(f)(x,y) = \begin{bmatrix} 2 & 0\\0 & 2 \end{bmatrix}$$

so that the function f(x, y) has the only critical point (1, 0) inside of D, and f has a local minimum f(1, 0) = 3 at this point.

Any point of the boundary of D can be written, in terms of polar coordinates, as

 $x = 2\cos\theta, \quad y = 2\sin\theta, \quad \theta \in [0, 2\pi).$ 

Hence

$$f(x,y) = f(2\cos\theta, 2\sin\theta) = 4 - 4\cos\theta + 4 = 4(2 - \cos\theta), \quad \theta \in [0, 2\pi),$$

on the boundary  $\partial D$ . When  $\cos \theta = 1$  (or  $\theta = 0$ ), f has the minimum 4, thus f has the minimum 4 at the point (2,0); when  $\cos \theta = -1$  (or  $\theta = \pi$ ), f has the maximum 12, thus f has the maximum 12 at the point (-2,0).

Therefore the absolute maxima and minima are 12 and 3 respectively.

- 8. Let  $f(x,y) = \sqrt{4x^2 + y^2}$  be a function of two variables.
- (a) Compute the directional derivative of the function f(x, y) at the point (-2, 4)

in the direction of  $\mathbf{v} = \begin{bmatrix} -3\\ -1 \end{bmatrix}$ .

(b) Find the angle between the vectors  $\nabla f(-2,4)$  and **v**.

The gradient vector of f is

$$\nabla f(x,y) = \begin{bmatrix} \frac{4x}{\sqrt{4x^2 + y^2}} \\ \frac{y}{\sqrt{4x^2 + y^2}} \end{bmatrix}$$

(a) The gradient of f at (-2, 4) is

$$\nabla f(-2,4) = \begin{bmatrix} \frac{-8}{4\sqrt{2}} \\ \frac{4}{4\sqrt{2}} \end{bmatrix} = \begin{bmatrix} \frac{-2}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

The normalization of  $\begin{bmatrix} -3\\ -1 \end{bmatrix}$  is

$$\mathbf{u} = \frac{1}{\left| \begin{bmatrix} -3\\ -1 \end{bmatrix} \right|} \begin{bmatrix} -3\\ -1 \end{bmatrix} = \frac{1}{\sqrt{10}} \begin{bmatrix} -3\\ -1 \end{bmatrix}$$

so that the directional derivative is equal to

$$D_{\mathbf{u}}f(-2.4) = \nabla f(-2.4) \cdot \mathbf{u} = \begin{bmatrix} \frac{-2}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \cdot \frac{1}{\sqrt{10}} \begin{bmatrix} -3 \\ -1 \end{bmatrix} = \frac{8}{\sqrt{20}} = \frac{4}{\sqrt{5}}$$

(b) Let  $\mathbf{w} = \nabla f(-2, 4)$ . Recall the formula

$$\cos\theta = \frac{\mathbf{w} \cdot \mathbf{v}}{|\mathbf{w}||\mathbf{v}|}$$

where  $\theta$  is the angle between **w** and **v**. The length of **w** is

$$|\mathbf{w}| = \sqrt{\frac{4}{2} + \frac{1}{2}} = \frac{\sqrt{5}}{\sqrt{2}}.$$

Hence

$$\cos \theta = \frac{\frac{6}{\sqrt{2}} - \frac{1}{\sqrt{2}}}{\frac{\sqrt{5}}{\sqrt{2}}\sqrt{10}} = \frac{1}{\sqrt{2}} = \frac{\sqrt{2}}{2}$$

Thus the angel is  $45^{\circ}$ .

**9.** Suppose you wish to enclose a rectangle plot. You have 1600 ft of fencing. Using the material, what are the dimensions of the plot that will have the largest area?

We wish to maximize

subject to the constraint 2x + 2y = 1600. Consider

 $f(x,y) = xy, \quad g(x,y) = 2x + 2y - 1600 = 0.$ 

A = xy

From

$$\nabla f(x,y) = \begin{bmatrix} y \\ x \end{bmatrix}, \quad \nabla g(x,y) = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$$

and the equation  $\nabla f(x, y) = \lambda \nabla g(x, y)$ , we have

 $y = 2\lambda, \quad x = 2\lambda, \quad x + y = 800,$ 

from which we get  $\lambda = 200$  and x = y = 400, with f(400, 400) = 160,000.

We now look at the boundary. By the physical reason, x, y > 0, so that we need only to consider the line segment x + y = 800 with 0 < x < 800. On this line segment, we have

$$f(x,y) = f(x,800-x) = x(800-x) = -x^2 + 800x, \quad 0 < x < 800.$$

The maximum value takes at (400, 400). Consequently, the largest area is f(400, 400) = 160,000.

**10.** Suppose that

$$\frac{dy}{dx} = y(2-y).$$

(a) Find the equilibria of this differential equation.

(b) Compute the eigenvalues associated with each equilibrium and discuss the stability of the equilibria.

Let g(y) = y(2 - y). Then g'(y) = 2 - 2y.

(a) The equilibria are y = 0 and y = 2.

(b) Since g'(0) = 2 > 0 and g'(2) = -2, the equilibrium 0 is unstable while 2 is locally stable.

Department of Mathematics, Johns Hopkins University, 3400 N Charles Street, Baltimore, MD 21218, USA

*E-mail address*: yli@math.jhu.edu