

**Lecture 9: 3.2 Fundamental Solutions of linear homogeneous equations.** Most of what we will do in this chapter concerns linear second order differential equations with constant coefficients. However, the results in this section also holds for variable coefficients. Let us first recall the **existence theorem**:

**Th 1** Suppose that  $p$ ,  $q$  and  $g$  are continuous on an open interval  $I = (a, b)$  containing  $t_0$ . Then the differential equation

$$(3.2.1) \quad y'' + p(t)y' + q(t)y = g(t)$$

has a unique solution on  $I$  satisfying

$$(3.2.2) \quad y(t_0) = y_0, \quad y'(t_0) = y'_0,$$

The proof basically reduces to the same proof as for the first order differential equation by rewriting it as a system. If we put

$$z = y', \quad z' = y'' = -p(t)y' - q(t)y + g(t) = -p(t)z - q(t)y + g(t)$$

we get a first order system for  $(y, z)$ :

$$\begin{aligned} y' &= z, & y(0) &= y_0 \\ z' &= f(t, y, z), & z(0) &= y_1 \end{aligned}$$

where

$$f(t, y, z) = -p(t)z - q(t)y - g(t),$$

which can be solved by writing it in integral form

$$\begin{aligned} y(t) &= y_0 + \int_{t_0}^t z(s) ds, \\ z(t) &= z_0 + \int_{t_0}^t f(s, y(s), z(s)) ds \end{aligned}$$

One can then use Piccard iteration, i.e. plugging in a guess for  $y(t)$  and  $z(t)$  in the right and getting a better guess in the left, the first guess simply being  $y_0$  and  $z_0$ .

Let us now introduce the operator notation;

$$L[\phi] = \phi'' + p\phi' + q\phi,$$

i.e. for each function  $\phi$ ,  $L[\phi]$  is the function who's value at at a point  $t$  is given by

$$L[\phi](t) = \phi''(t) + p(t)\phi'(t) + q(t)\phi(t)$$

$L$  is called an operator because it maps functions to functions.

We also proved the **superposition principle** for linear equations in last lecture:

**Th 2** If  $y_1$  and  $y_2$  are solutions to

$$L[y] = y'' + p(t)y' + q(t)y = 0$$

then so is

$$(3.2.3) \quad c_1 y_1 + c_2 y_2$$

Basically, this section is about finding a condition on  $y_1$  and  $y_2$  that guarantee that all solutions are of the form  $y = c_1 y_1 + c_2 y_2$  for some constants  $c_1$  and  $c_2$ . We therefore define the **Wronskian determinant** of two solutions by:

$$(3.2.4) \quad W = y_1 y_2' - y_1' y_2$$

**Th 3** If  $W(t_0) \neq 0$  then one can find  $c_1$  and  $c_2$  such that (3.2.3) satisfies (3.2.2).

**Proof of Th 3** We must solve the following system for the unknowns  $c_1$  and  $c_2$ :

$$(3.2.5) \quad \begin{aligned} c_1 y_1(t_0) + c_2 y_2(t_0) &= y_0 \\ c_1 y_1'(t_0) + c_2 y_2'(t_0) &= y_0' \end{aligned}$$

Each equation represent a line in the  $(c_1, c_2)$  plane and the system can be solved as long as the lines intersect and are not parallel. This happens when the vectors  $(y_1(t_0), y_2(t_0))$  and  $(y_1'(t_0), y_2'(t_0))$  are not parallel, which is the case if (3.2.4) is different from 0 at  $t_0$ . However, you can also see that the Wronskian comes in by trying to solve the system. If we multiply the first equation by  $y_2'(t_0)$  and the second by  $y_2(t_0)$  and subtract we get

$$c_1 (y_2' y_1 - y_2 y_1') = y_2' y_0 - y_2 y_0'$$

and in general this can only be solved for  $c_1$  if  $W = y_2' y_1 - y_2 y_1' \neq 0$ . Similarly for  $c_2$

**Th 4** If  $W(t_0) \neq 0$  for some  $t_0$  then all solutions are of the form  $y = c_1 y_1 + c_2 y_2$ .

**Proof** This follows from Theorem 3 and the uniqueness in Theorem 1.

**Definition**  $y_1$  and  $y_2$  are called a **fundamental set of solutions** if all solution can be written as  $c_1 y_1 + c_2 y_2$ .

**Ex** Consider the equation  $ay'' + by' + cy = 0$ . Let  $r_1$  and  $r_2$  be the roots of the characteristic equation  $ar^2 + br + c = 0$ . Then  $y_1 = e^{r_1 t}$  and  $y_2 = e^{r_2 t}$  are both solutions. The Wronskian is  $W = y_2' y_1 - y_2 y_1' = (r_2 - r_1) e^{(r_1 + r_2)t} \neq 0$  if and only if  $r_1 \neq r_2$ . Hence  $y_1$  and  $y_2$  form a fundamental set of solutions if and only if  $r_1 \neq r_2$ .

It turns out that we can always find two different solutions.

**Th 5** Let  $y_1$  and  $y_2$  be two solutions of  $L[y] = 0$  satisfying the initial conditions

$$y(t_0) = 1, \quad y_1'(t_0) = 0, \quad y_2(t_0) = 0, \quad y_2'(t_0) = 1$$

Then  $W = y_2' y_1 - y_2 y_1' = 1 \neq 0$ .

If the roots  $r_1$  and  $r_2$  are complex then  $e^{r_1 t}$  and  $e^{r_2 t}$  are in fact complex solutions if we define the exponential function for complex numbers right. We want to investigate what it means to be a **complex solution**. Suppose that  $p$  and  $q$  are real valued and let

$$y(t) = u(t) + i v(t)$$

be a complex function, where  $u$  and  $v$  are real and  $i = \sqrt{-1}$ . The derivative of a complex function is given by

$$y'(t) = u'(t) + i v'(t)$$

and similar for second order derivatives so

$$L[y] = L[u] + i L[v]$$

It follows that if  $L[y] = 0$  then  $L[u] = 0$  and  $L[v] = 0$ .