

THE JOHNS HOPKINS UNIVERSITY  
Krieger School of Arts and Sciences  
SECOND MIDTERM EXAM - FALL 2005  
110.201 - LINEAR ALGEBRA

Instructor: Professor Carel Faber  
Duration: 50 minutes      November 22, 2005

No calculators allowed

Total = 100 points

NAME: *Carel Faber*

SECTION (weekday and time): *1,2,3,4*

ETHICS PLEDGE:

I agree to complete this examination without unauthorized assistance from any person, materials, or device.

SIGNATURE:

DATE:

1. [25 points] Let  $P_1$  be the linear space of polynomials  $f(t)$  of degree  $\leq 1$ . Let  $T$  from  $P_1$  to  $P_1$  be the linear transformation given by

$$T(-1) = -5 - 2t \quad \text{and} \quad T(1 + 2t) = -3.$$

- (a) [7 points] Find the matrix  $A$  of  $T$  with respect to the standard basis  $\mathcal{A} = (1, t)$ .  $T(-1) = -T(1)$  so  $T(1) = -T(-1) = 5 + 2t$

$$T(2t) = T(-1) + T(1 + 2t) = -5 - 2t - 3 = -8 - 2t, \text{ so}$$

$$T(t) = \frac{1}{2} T(2t) = -4 - t.$$

$$\text{So 1st col. of } A = [T(1)]_{\mathcal{A}} = \begin{pmatrix} 5 \\ 2 \end{pmatrix},$$

$$\text{2nd col. of } A = [T(t)]_{\mathcal{A}} = \begin{pmatrix} -4 \\ -1 \end{pmatrix}, \text{ so } A = \begin{pmatrix} 5 & -4 \\ 2 & -1 \end{pmatrix}.$$

- (b) [8 points] Find the matrix  $B$  of  $T$  with respect to the basis  $\mathcal{B} = (1 + t, 2 + t)$ .

$$T(1 + t) = T(1) + T(t) = 1 + t \quad (\text{hey!})$$

$$T(2 + t) = T(2) + T(t) = 10 + 4t - 4 - t = 6 + 3t = 3(2 + t) \quad (\text{hey!}).$$

$$\text{As above: 1st col. of } B = [T(1 + t)]_{\mathcal{B}} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\text{2nd col. of } B = [T(2 + t)]_{\mathcal{B}} = \begin{pmatrix} 0 \\ 3 \end{pmatrix}, \text{ so } B = \begin{pmatrix} 1 & 0 \\ 0 & 3 \end{pmatrix}.$$

[Note:  $A$  has been diagonalized w.r.t. the basis  $\mathcal{B}$ , it is an eigenbasis!]

- (c) [5 points] Find the change of basis matrix  $S$  from the basis  $\mathcal{B}$  to the basis  $\mathcal{A}$ .

$$\left. \begin{array}{l} \text{1st col. of } S = [1 + t]_{\mathcal{A}} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ \text{2nd col. of } S = [2 + t]_{\mathcal{A}} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \end{array} \right\} S = \begin{pmatrix} 1 & 2 \\ 1 & 1 \end{pmatrix}$$

Note:  $S$  is made from eigenvectors for  $A$  in this case, since  $B$  is diagonal.

$$\text{Easy to check: } AS = SB.$$

(d) [5 points] Is  $SBS^{-1}$  equal to  $A$ ? Motivate your answer.

① by computation:  $S^{-1} = \frac{1}{\det(S)} \begin{pmatrix} 1 & -2 \\ -1 & 1 \end{pmatrix} = \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix}$

$$BS^{-1} = \dots = \begin{pmatrix} -1 & 2 \\ 3 & -3 \end{pmatrix}$$

$$SBS^{-1} = \dots = \begin{pmatrix} 5 & -4 \\ 2 & -1 \end{pmatrix} = A, \text{ Yes!}$$

② If you understood what happened in (b) and (c), then  
 $AS = SB$  so  $SBS^{-1} = A$ . (← Preferred solution.)

2. [25 points] Find the determinant of the matrix

$$A = \begin{bmatrix} 1 & 1 & 0 & 1 & 1 \\ 0 & 2 & 0 & 7 & 0 \\ 2 & 3 & 4 & 5 & 0 \\ 0 & 0 & 0 & 3 & 0 \\ 3 & 4 & 5 & 2 & 6 \end{bmatrix}.$$

$$\det A = (+3) \begin{vmatrix} 1 & 1 & 0 & 1 \\ 0 & 2 & 0 & 0 \\ 2 & 3 & 4 & 0 \\ 3 & 4 & 5 & 6 \end{vmatrix}$$

(develop ~~the~~ <sup>also</sup> the 4<sup>th</sup> row)

$$= 3 \cdot (+2) \cdot \begin{vmatrix} 1 & 0 & 1 \\ 2 & 4 & 0 \\ 3 & 5 & 6 \end{vmatrix} \quad (\text{develop along the 2<sup>nd</sup> row})$$

$$= 6 \left( 1 \cdot 4 \cdot 6 + 2 \cdot 5 \cdot 1 + 3 \cdot 0 - 1 \cdot 4 \cdot 3 - 0 - 0 \right)$$

$$= 6 (24 + 10 - 12) = 6 \cdot 22 = 132.$$

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3. [25 points] Consider the linear space  $P_1$  of polynomials of degree  $\leq 1$  with inner product

$$\langle f, g \rangle = \int_0^1 f(t)g(t)dt.$$

- (a) [5 points] Determine the norm of the element  $f(t) = 1$  of  $P_1$ .

By def., norm of 1 =  $\|1\| = \sqrt{\langle 1, 1 \rangle}$ .

$$\text{Now } \langle 1, 1 \rangle = \int_0^1 1 \cdot 1 dt = \int_0^1 1 dt = [t]_0^1 = 1 - 0 = 1.$$

$$\text{So } \|1\| = \sqrt{1} = 1.$$

(Do not take this for granted! With  $\int_0^2 f(t)g(t)dt$ ,

$$\|1\| = \sqrt{2} \quad !)$$

- (b) [5 points] Show that  $g(t) = 2t - 1$  is orthogonal to  $f(t)$ .

$$\begin{aligned} \langle g(t), f(t) \rangle &= \langle 2t - 1, 1 \rangle = \int_0^1 (2t - 1) dt = [t^2 - t]_0^1 \\ &= 1 - 1 - 0 + 0 = 0. \quad \underline{\text{QED.}} \end{aligned}$$

(c) [5 points] Determine the norm of the element  $g(t)$  of  $P_1$ .

$$\begin{aligned} \langle g(t), g(t) \rangle &= \int_0^1 (2t-1)^2 dt = \int_0^1 (4t^2 - 4t + 1) dt \\ &= \left[ \frac{4}{3}t^3 - 2t^2 + t \right]_0^1 = \frac{4}{3} - 2 + 1 = \frac{7}{3} - 2 = \frac{1}{3} \end{aligned}$$

$$\|g(t)\| = \sqrt{\frac{1}{3}} = \frac{1}{\sqrt{3}} = \frac{1}{3}\sqrt{3} \quad (\text{all 3 answers fine}).$$

(d) [10 points] Find the linear polynomial  $k(t) = a + bt$  that best approximates the function  $h(t) = t^2 - t$  on the interval  $[0, 1]$  in the (continuous) least-squares sense.

This is done with a projection; we need  $\text{proj}_{\langle 1, t \rangle}(h(t))$ . Best done with an ONB for

$$\langle 1, t \rangle; \text{ now } f(t) \perp g(t), \|f(t)\| = 1, \|g(t)\| = \frac{1}{\sqrt{3}}. \text{ So } u_1 = f(t) \text{ and } u_2 = \frac{g(t)}{\|g(t)\|}$$

$$= \sqrt{3}g(t) = \sqrt{3}(2t-1) \text{ form an ONB!}$$

Then  $\text{proj}(h(t)) = \langle u_1, h(t) \rangle u_1 + \langle u_2, h(t) \rangle u_2$ . But

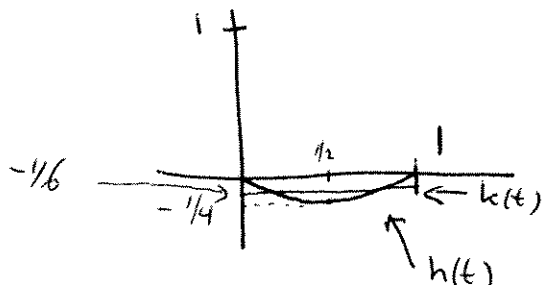
$$\langle u_1, h(t) \rangle = \int_0^1 h(t) dt = \int_0^1 (t^2 - t) dt = \left[ \frac{1}{3}t^3 - \frac{1}{2}t^2 \right]_0^1 = \frac{1}{3} - \frac{1}{2} = -\frac{1}{6}$$

And  $\langle u_2, h(t) \rangle = \int_0^1 \sqrt{3}(2t-1)(t^2-t) dt = \sqrt{3} \int_0^1 (2t^3 - 3t^2 + t) dt$

$$= \sqrt{3} \left[ \frac{2}{4}t^4 - t^3 + \frac{1}{2}t^2 \right]_0^1 = \sqrt{3} \left( \frac{1}{2} - 1 + \frac{1}{2} \right) = 0.$$

So  $k(t) = \text{proj}(h(t)) = -\frac{1}{6}u_1 = -\frac{1}{6}$  (answer).

To understand it, picture:



$k(t)$  is the best linear function on  $[0, 1]$  approximating  $h(t)$ . Note that  $h(t)$  is symmetric wrt. reflection in the midpoint  $t = \frac{1}{2}$ . So the same holds for  $k(t)$ ,  $k(t)$  is horizontal. Finally,  $\int_0^1 k(t) dt = \int_0^1 h(t) dt$  and  $k(t) = -1/6$  is best

4. [25 points] Consider the matrix

$$A = \begin{bmatrix} -3 & 0 & 4 \\ 0 & -1 & 0 \\ -2 & 7 & 3 \end{bmatrix}.$$

(a) [5 points] Find all real eigenvalues of  $A$ , with their algebraic multiplicities.

$$\begin{aligned} 0 &= \begin{vmatrix} -3-\lambda & 0 & 4 \\ 0 & -1-\lambda & 0 \\ -2 & 7 & 3-\lambda \end{vmatrix} \stackrel{\substack{\text{develop} \\ \text{2nd row}}}{=} (-1-\lambda) \begin{vmatrix} -3-\lambda & 4 \\ -2 & 3-\lambda \end{vmatrix} \\ &= -(\lambda+1) \left( (\lambda-3)(\lambda+3) + 8 \right) = -(\lambda+1) (\lambda^2 - 9 + 8) \\ &= -(\lambda+1) (\lambda^2 - 1) = -(\lambda+1)^2 (\lambda-1). \end{aligned}$$

Eigenvalues:  $-1$ , with alg.-mult. 2;  
 $1$ , with alg.-mult. 1.

(b) [5 points] For each eigenvalue of  $A$ , find a basis of the associated eigenspace. What are the geometric multiplicities of the eigenvalues of  $A$ ?

$$\underline{\lambda_1 = 1}: \text{Ker}(A - I) = \text{Ker} \begin{pmatrix} -4 & 0 & 4 \\ 0 & -2 & 0 \\ -2 & 7 & 2 \end{pmatrix}. \text{ Need } \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$\text{with } \begin{pmatrix} -4 & 0 & 4 \\ 0 & -2 & 0 \\ -2 & 7 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0; \text{ then } -2x_2 = 0 \Rightarrow x_2 = 0$$

and  $-4x_1 + 4x_3 = 0 \Rightarrow x_3 = x_1$ , & that's it!  
 So e.g.  $\vec{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$  is a basis. Geom.-mult. 1 (is obvious).

$$\underline{\lambda_2 = -1}: \text{Ker}(A + I) = \text{Ker} \begin{pmatrix} -2 & 0 & 4 \\ 0 & 0 & 0 \\ -2 & 7 & 4 \end{pmatrix}; \quad x_1 = 2x_3, \text{ and } x_2 = 0;$$

So  $\vec{v}_2 = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}$  is a basis. Geom.-mult. 1 (not obvious from the start).

(c) [5 points] Does there exist an eigenbasis for the matrix  $A$ ? Motivate your answer.

No: only 2 independent eigenvectors.

Or: No, since sum of geom. mult.'s =  $1+1$   
 $= 2 < 3 = \text{size of matrix } A = \dim \mathbb{R}^3$ .

(d) [5 points] Is  $A$  diagonalizable? Motivate your answer.

No, since a matrix is diagonalizable if and only if there exists an eigenbasis for it.

(e) [5 points] Determine the eigenvalues of  $A^2$ , with their algebraic and geometric multiplicities.

One can compute  $A^2$  (do it correctly!) but it's more fun to think a little:

in general, if  $A\vec{v} = \lambda\vec{v}$ , then  $A^2\vec{v} = A(A\vec{v}) = A(\lambda\vec{v})$   
 $= \lambda(A\vec{v}) = \lambda(\lambda\vec{v}) = \lambda^2\vec{v}$ .

So: if  $\vec{v}$  is an eigenvector for  $A$ , with e-value  $\lambda$ , then  $\vec{v}$  is an eigenvector for  $A^2$ , with e-value  $\lambda^2$ .

So:  $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$  is an e-vector for  $A^2$  with e-value  $1^2 = 1$ ;

$\begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix}$  is an e-vector for  $A^2$  with e-value  $(-1)^2 = 1$ ;

So the geom. mult. of **1** is at least 2.

But:  $\det(A) = (-1)^2 \cdot 1 = \text{product of e-values with alg. mult.}$

So  $\det(A^2) = \det(A) \det(A) = 1^2 = 1 = 1 \cdot 1 \cdot (\text{3rd eigenvalue})$ ;

So alg. mult. of 1 is 3. Finally, if geom. mult. = 3, then  $A^2 = I$ . But easy to see that  $A^2 \neq I$ .  
So geom. mult. is 2.