

## Doob's $h$ -Transform: Exercise 7.14(b)

**Problem statement.** Let  $B_t$  be  $n$ -dimensional Brownian motion, let  $D \subset \mathbb{R}^n$  be a bounded open set, and let  $h > 0$  be harmonic on  $D$ , i.e.

$$\Delta h = 0 \quad \text{in } D.$$

Consider the stochastic differential equation

$$dX_t = \nabla(\log h)(X_t) dt + dB_t. \quad (1)$$

Since the drift  $\nabla(\log h)$  need not be globally well-behaved near  $\partial D$ , the solution is defined up to its lifetime by exhaustion of  $D$ . That is, choose an increasing sequence of open sets  $\{D_k\}_{k \geq 1}$  such that  $\overline{D_k} \subset D$  and  $\bigcup_{k=1}^{\infty} D_k = D$ . For each  $k$ , let

$$\tau_{D_k} := \inf\{t \geq 0 : X_t \notin D_k\}, \quad \tau := \lim_{k \rightarrow \infty} \tau_{D_k}.$$

Because  $\nabla(\log h)$  is Lipschitz on  $\overline{D_k}$ , Eq.(1) has a unique strong solution on  $[0, \tau_{D_k})$ . By uniqueness these local solutions are compatible for different  $k$ , and therefore define a process  $X_t$  on  $[0, \tau)$ . This  $\tau$  is the lifetime of the solution.

Assume now that there exists  $x_0 \in \partial D$  such that

$$\lim_{x \rightarrow y, x \in D} h(x) = \begin{cases} 0, & y \in \partial D, y \neq x_0, \\ \infty, & y = x_0. \end{cases} \quad (2)$$

Prove that

$$\lim_{t \uparrow \tau} X_t = x_0 \quad \text{a.s.}$$

*Proof.* We divide the proof into four steps.

**Step 1: A harmonic test function for the generator.** By part (a), the generator  $A$  of  $X_t$  satisfies

$$Au = \frac{\Delta(hu)}{2h}, \quad u \in C_0^2(D). \quad (3)$$

In particular, if  $u = 1/h$ , then  $Au = \frac{\Delta(hu)}{2h} = \frac{\Delta 1}{2h} = 0$ .

**Step 2: Excluding compact subsets of  $\partial D \setminus \{x_0\}$ .** Let  $F \subset \partial D \setminus \{x_0\}$  be compact. We show that

$$\mathbb{P}^x(E_F) = 0, \quad E_F := \{X_t \text{ has a cluster point in } F \text{ as } t \uparrow \tau\}. \quad (4)$$

Since  $h(x) \rightarrow 0$  as  $x \rightarrow y \in F$  from within  $D$ , we have

$$u(x) = \frac{1}{h(x)} \rightarrow \infty \quad \text{as } x \rightarrow y \in F.$$

Then, for each  $N \geq 1$ , there exists an open neighborhood  $U_N$  of  $F$  in  $\overline{D}$  such that

$$u(z) \geq N, \quad z \in U_N \cap D.$$

Define the stopping time

$$\sigma_N := \inf\{t < \tau : X_t \in U_N \cap D\}.$$

For fixed  $k$  and  $t > 0$ , let

$$T_{t,N,D_k} := \sigma_N \wedge \tau_{D_k} \wedge t.$$

Since  $Au = 0$ , Dynkin's formula gives

$$\mathbb{E}^x[u(X_{T_{t,N,D_k}})] = u(x).$$

On the event  $\{\sigma_N < \tau_{D_k}, \sigma_N \leq t\}$ , we have  $X_{T_{t,N,D_k}} = X_{\sigma_N} \in U_N \cap D$ , so  $u(X_{T_{t,N,D_k}}) \geq N$  and hence

$$u(x) = \mathbb{E}^x[u(X_{T_{t,N,D_k}})] \geq N \mathbb{P}^x(\sigma_N < \tau_{D_k}, \sigma_N \leq t).$$

Letting  $t \rightarrow \infty$  yields

$$u(x) \geq N \mathbb{P}^x(\sigma_N < \tau_{D_k}).$$

Letting  $k \rightarrow \infty$  and using the fact that  $\tau_{D_k} \uparrow \tau$ , we have

$$u(x) \geq N \mathbb{P}^x(\sigma_N < \tau).$$

If  $E_F$  in (4) occurs, then for every neighborhood  $U_N$  of  $F$ , the path must enter  $U_N \cap D$  before time  $\tau$ . Hence,  $E_F \subset \{\sigma_N < \tau\}$  for every  $N$ . Using the previous inequality, we get

$$\mathbb{P}^x(E_F) \leq \mathbb{P}^x(\sigma_N < \tau) \leq \frac{u(x)}{N}, \quad \forall N.$$

Letting  $N \rightarrow \infty$ , we obtain  $\mathbb{P}^x(E_F) = 0$ .

**Step 3: The only possible boundary cluster point is  $x_0$ .** For  $m \geq 1$ , define

$$F_m := \{y \in \partial D : |y - x_0| \geq 1/m\}.$$

Each  $F_m$  is compact and contained in  $\partial D \setminus \{x_0\}$ . By Step 2,

$$\mathbb{P}^x(X_t \text{ has a cluster point in } F_m \text{ as } t \uparrow \tau) = 0, \quad m \geq 1.$$

Since  $\partial D \setminus \{x_0\} = \bigcup_{m=1}^{\infty} F_m$ , it follows that, almost surely,  $X_t$  has no cluster point in  $\partial D \setminus \{x_0\}$ .

**Step 4: Conclusion.** Because  $D$  is bounded,  $\bar{D}$  is compact, so every path  $\{X_t : 0 \leq t < \tau\}$  has at least one cluster point in  $\bar{D}$  as  $t \uparrow \tau$ . Moreover, no cluster point can lie in  $D$ : if  $X_{t_j} \rightarrow z \in D$  along some sequence  $t_j \uparrow \tau$ , then for some ball  $B(z, r) \Subset D$  the coefficients of (1) are smooth on  $B(z, r)$ , so the solution can be continued beyond  $\tau$ , contradicting maximality of the lifetime. Hence every cluster point lies on  $\partial D$ .

Step 3 shows that the only possible boundary cluster point is  $x_0$ . Therefore,  $\lim_{t \uparrow \tau} X_t = x_0$  a.s., and this completes the proof.  $\square$

**Remark.** *The diffusion with drift  $\nabla \log h$  may be viewed as Brownian motion in  $D$  conditioned to exit the domain at the distinguished boundary point  $x_0$ .*

**Example** (A standard example of  $h$ ). *Let*

$$D = B(0, 1) \subset \mathbb{R}^n, \quad x_0 \in \partial B(0, 1), \quad |x_0| = 1,$$

and define

$$h(x) = \frac{1 - |x|^2}{|x - x_0|^n}, \quad x \in B(0, 1).$$

*Up to a multiplicative constant, this is the Poisson kernel of the unit ball with pole at  $x_0$ . It satisfies:*

- $h(x) > 0$  for  $x \in B(0, 1)$  and  $h$  is harmonic in  $B(0, 1)$ ;
- if  $y \in \partial B(0, 1)$  and  $y \neq x_0$ , then  $h(x) \rightarrow 0$  as  $x \rightarrow y$ ,  $x \in B(0, 1)$ ;

- if  $x \rightarrow x_0$  from within  $B(0, 1)$ , then  $h(x) \rightarrow \infty$ .

Thus  $h$  satisfies condition (2) in the problem statement. In dimension  $n = 2$ , for instance with  $x_0 = (1, 0)$ ,  $h(x) = \frac{1-|x|^2}{|x-(1,0)|^2}$ .

To verify directly that  $h$  is harmonic in  $B(0, 1)$ , write

$$a := x_0, \quad |a| = 1, \quad f(x) := 1 - |x|^2, \quad g(x) := |x - a|^{-n},$$

so that  $h = fg$ . Since  $a \in \partial B(0, 1)$ , the point  $a$  is not in the open ball, hence  $g$  is smooth on  $B(0, 1)$ . Now, with  $r = |x - a|$ ,

$$\begin{aligned} \nabla f(x) &= -2x, & \Delta f(x) &= -2n, \\ \nabla g(x) &= -nr^{-n-2}(x - a), & \Delta g(x) &= 2nr^{-n-2}. \end{aligned}$$

Therefore, by the product rule,

$$\begin{aligned} \Delta h &= f \Delta g + 2 \nabla f \cdot \nabla g + g \Delta f = 2n(1 - |x|^2)r^{-n-2} + 4nx \cdot (x - a)r^{-n-2} - 2nr^{-n} \\ &= 2nr^{-n-2} \left[ (1 - |x|^2) + 2x \cdot (x - a) - |x - a|^2 \right] = 0, \end{aligned}$$

because the term in the bracket is

$$1 - |x|^2 + 2|x|^2 - 2x \cdot a - (|x|^2 - 2x \cdot a + |a|^2) = 1 - |a|^2 = 0.$$