

110.302 Lecture 8 : 9/18/15 I

## Bifurcations

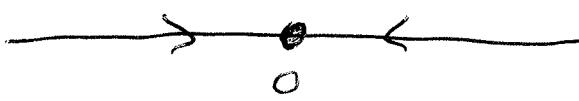
Consider the autonomous  $\dot{y} = f(\alpha, y)$  where " $\alpha$ " is a parameter (or unknown constant).

The number and classification of equilibria may depend on the value of " $\alpha$ ".

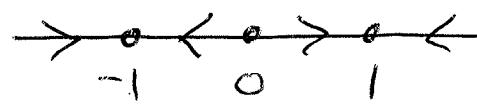
ex.  $\dot{y} = \alpha y - y^3 = y(\alpha - y^2)$

Here, for  $\alpha < 0$  and  $\alpha > 0$  the number of equilibria are different (also the type)

$$\alpha = -1 < 0$$



$$\alpha = 1 > 0$$



$$\text{Here } f(-1, y) = -y(1+y^2)$$

and  $y(t) \equiv 0$  is the only equilibrium.

It is asymptotically stable

$$\text{Here } f(1, y) = y(1-y^2)$$

$$= y(1-y)(1+y)$$

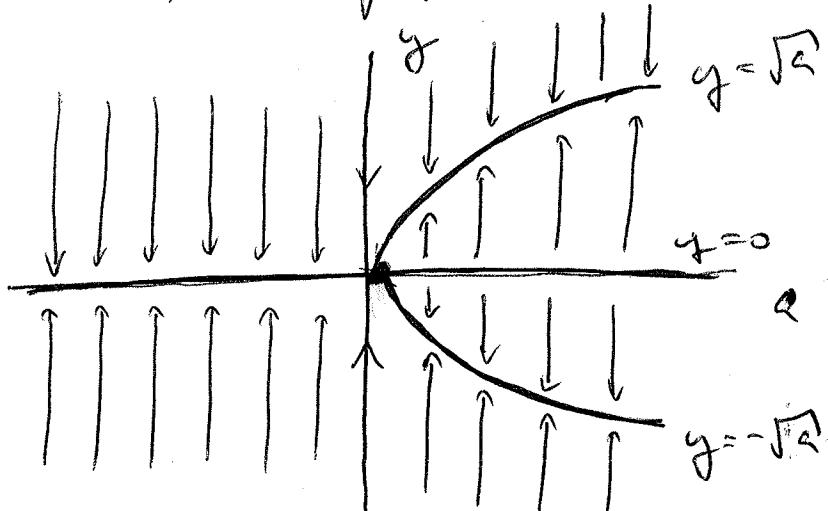
and equilibria exist at  $y = -1, 0, 1$ .  $y(t) \equiv 0$  is unstable here.

We can study how the parameter affects equilibrium via a bifurcation diagram:

a graph of equilibria in relation to parameter value in the  $\alpha\gamma$ -plane for  $y' = f(\alpha, y)$ .

### Properties

- each vertical slice here is the phase line of  $y' = f(\alpha, y)$  for that value of " $\alpha$ ".
- As  $\alpha$  varies, equilibria trace out curves of fixed str. Found by solving  $f(\alpha, y) = 0$ .
- Special values of " $\alpha$ " where the number of equilibria and/or the stability change are called bifurcation values of " $\alpha$ ".
- Here, the curves for  $\alpha > 0$  correspond to ~~two~~ solutions to  $f(\alpha, y) = y(\alpha - y^2) = 0$ , or to  $\boxed{y=0}$  and  $\alpha = y^2$  or  $\boxed{y = \pm\sqrt{\alpha}}$

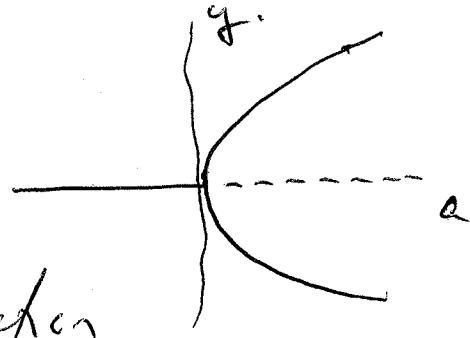


III

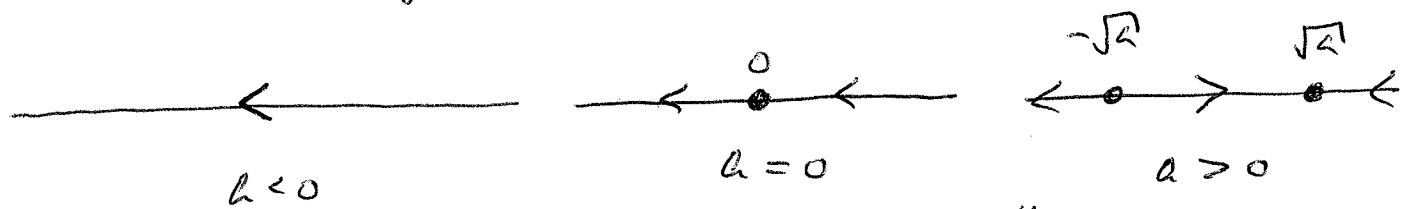
- Here, the only bifurcation value of  $\alpha$  is  $\alpha = 0$ .
- Here we use solid lines for all equilibria, and vertical arrows to denote stability.

Back over solid for asympt. stable curves and dotted for unstable curves.

- This kind of bifurcation is called a **pitchfork bifurcation**.  
why?



ex.  $\dot{y} = \alpha - y^2$



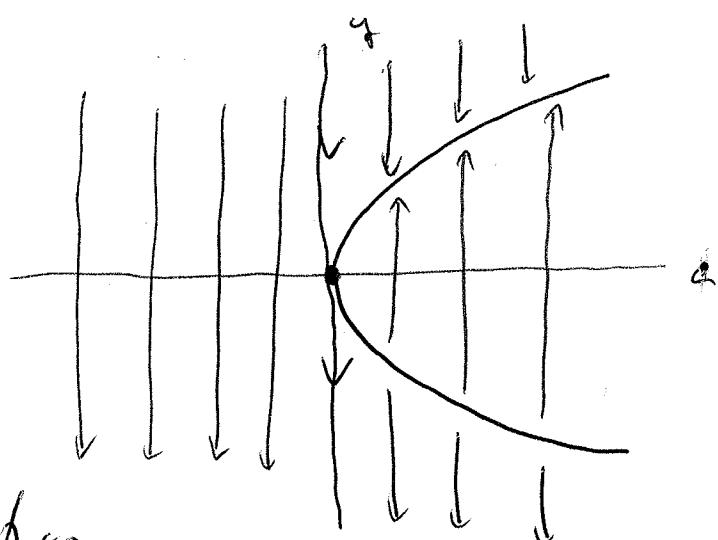
Lines of equilibria

solve  $\alpha = y^2$  or

$y = \sqrt{\alpha}, y = -\sqrt{\alpha}$

only for  $\alpha \geq 0$

Called a **saddle-node**  
or **creation** bifurcation



ex. Basic model of a Laser (simple) IV

$$\dot{n} = (\alpha N_0 - k)n - \gamma n^2$$

models a basic single laser, where

$n(t)$  = # of photons at time  $t$

$N_0, k, \gamma$  are positive constants

We study how the eqn is affected by  $N_0 \geq 0$

Here equilibrium is at

$$n(\alpha N_0 - k - \gamma n) = 0$$

namely  $n=0$

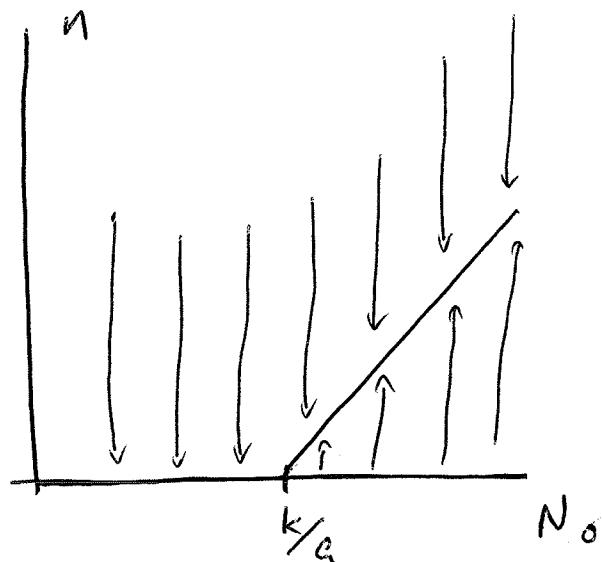
$$n = N_0 - \frac{k}{\gamma}$$

① When  $N_0 < \frac{k}{\gamma}$ ,

$$(\alpha N_0 - k) < 0,$$

so  $\dot{n} < 0$ .

$n(t) \equiv 0$  is a sink.



② When  $N_0 > \frac{k}{\gamma}$ ,  $\alpha N_0 - k > 0 \Rightarrow$  for small  $n$ ,

$$\alpha N_0 - k - \gamma n > 0, \text{ or } N_0 - \frac{k}{\gamma} - n > 0, \text{ so}$$

for small  $n$ ,  $\dot{n} > 0$ . etc.

## Change track

Recall for any ~~equation~~ involving  $x, y$ ,

- we can bring all terms to one side of the equation and create an equivalent equation

$$\varphi(x, y) = 0$$

for  $\varphi(x, y)$  a function of 2 variables. Then the curve in the  $xy$ -plane satisfying this equation is called the 0-level set of  $\varphi$ .

ex.  $y^2 = 1 - x^2$ . We view this eqn as the 0-level set of the function  $\varphi(x, y) = x^2 + y^2 - 1 = 0$

- We can view  $y$  as an implicit function of  $x$ .

In either case, the ~~graph~~ of the original equation (or the  $\varphi(x, y) = 0$ ) is a curve in  $xy$ -plane that in general will not look like a function.

We can calculate the tangent lines to this graph via differentiation in either interpretation:

ex.  $x^2 + xy^2 = 4$ , or  $\varphi(x, y) = 0$ ,  $\varphi(x, y) = x^2 + xy^2 - 4$

Implicit diff  $\frac{d}{dx}(x^2 + xy^2 - 4) \Rightarrow \cancel{2x + y^2} + 2xy \frac{dy}{dx} = 0$

Calc III  $\frac{dy}{dx}(x, y) = \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \cdot \frac{dy}{dx} = \frac{\partial \varphi}{\partial x} + \underbrace{\frac{\partial \varphi}{\partial y} \cdot y}_*$

when we think of  $y$  as an implicit func of  $x$ .

Suppose a first-order ODE is of the form

$$M(x, y) + N(x, y) y' = 0 \quad (*)$$

Then  $(*)$  and  $(*)$  are the same under the condition that there exists a function

$\varphi(x, y)$ , where ①  $\frac{\partial \varphi}{\partial x}(x, y) = M(x, y)$

②  $\frac{\partial \varphi}{\partial y}(x, y) = N(x, y)$

So that  $(M(x, y) + N(x, y) y') = \frac{dy}{dx} = \frac{\partial \varphi}{\partial x} = \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} y'$

If this is the case, then the ODE (4)

can be rewritten as  $\frac{dy}{dx} = 0$ , or

$$\Psi(x, y) = C, \text{ a constant.}$$

Thus, solving the ODE at least implicitly.

Ex 1 (at).

Notice that  $2x + y^2 + 2xyy' = 0$  is of the form  $M(x, y) + N(x, y)y' = 0$  with

$$M(x, y) = 2x + y^2$$

$$N(x, y) = 2xy.$$

But we also can see that the function  $\Psi(x, y) = x^2 + xy^2$  has the partials

$$\frac{\partial \Psi}{\partial x}(x, y) = 2x + y^2 \quad \frac{\partial \Psi}{\partial y}(x, y) = 2xy.$$

Hence  $2x + y^2 + 2xyy' = 0$  can be written

$$\frac{dy}{dx} = 0 = \frac{1}{2x}(x^2 + 2xy^2)$$

If we assume that  $y$  is an implicit function of  $x$ .

IV

Here we can (assuming  $y$  is an implicit  
function of  $x$ ) integrate  $\frac{dy}{dx}(x,y) = 0$  wst  $x$   
to get

$$\int \frac{dy}{dx}(x,y) dx = \int 0 dx$$

$$y(x,y) = x^2 + xy^2 = C$$

This is the general implicit solution to

$$2x + y^2 + 2xyy' = 0$$


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Q: How do we know such a  $y(x,y)$  may exist  
and if so how to find it?

Calc III Then Let  $y(x,y)$  have continuous partial  
derivatives in some open region. Then

$$\frac{\partial}{\partial x} \left( \frac{\partial y}{\partial y} \right) = \frac{\partial}{\partial y} \left( \frac{\partial y}{\partial x} \right)$$

i.e. Mixed partials are equal.