

Compare the following:

$$\textcircled{a} \quad \frac{dy}{dx} = x - e^{x^2} \quad \textcircled{b} \quad \frac{dp}{dt} = \frac{p}{2} - 450$$

- ① Both are ~~not~~ First order ODEs.
 - ② Both are linear (can you ~~see~~ see this?)
 - ③ ② is of the form $y' = f(x)$ independent variable on RHS
and is simply a calculus problem
(think: find $\int f(x) dx$) ~~for y~~.
- Here the RHS is only a func of the independent variable.

- Integrate both sides with respect to x to get

$$y(x) = \frac{x^2}{2} - 2e^{x^2} + C$$

- This formula is called a general solution to ② as it is an expression that specifies all possible solutions.

- A particular solution to $\textcircled{2}$ involves choosing a value for the constant c .
 - Graphs of solutions are called integral curves (why?)
- Some integral curves of $\textcircled{2}$
- where each is a particular solution

- We also call the general solution to $\textcircled{2}$ a 1-parameter family of solutions.

With the addition of a single pt in the xy -plane (ex. $y(0)=2$), called an initial value, we can "choose" a particular solution from the family.

III

With this point, there is now only 1 solution to the problem:

$$y(x) = \frac{x^2}{2} - 2e^{x_2} + C$$

$$y(0) = \frac{0^2}{2} - 2e^{0_2} + C = 2$$

$$= 0 - 2 + C = 2 \Rightarrow C = 4$$

Hence the solution to the Initial Value Problem
(an ODE with initial values)

$$\underbrace{y' = x - e^{x_2}, \quad y(0) = 2}_{\text{IVP}} \quad \text{or} \quad y(x) = \frac{x^2}{2} - 2e^{x_2} + 4.$$

See the red curve above.

④ ③ is not of the form $y' = f(x)$.

Rather, it is of the form $y' = f(y)$ dependent variable on RHS.
(in this case $p' = f(p)$)

Note: This is harder to solve but easier to sketch!

Def: if in an ODE the independent variable is NOT explicitly present, the ODE is called autonomous.

Let's solve ⑥: There are many ways. We choose something like what we will eventually call "separation of variables".

First, recall from Calculus I,

① For any diff. p(t), the functions $p(t)$ and $p(t) - 900$ have the same derivative: $p'(t)$.

② $\frac{d}{dt} [\ln |f(t)|] = \frac{f'(t)}{f(t)}$ for $f(t)$ differentiable and $f(t) \neq 0$.
(chain Rule)

Hence we can rewrite $p' = \frac{p}{2} - 450 = \frac{p - 900}{2}$.

or $\frac{p'}{p - 900} = \frac{1}{2}$. Why is this useful?

V

It is useful since the LHS of $\frac{p'}{p-q_00} = \frac{1}{2}$
looks like the derivative

$$\frac{d}{dt} [\ln |p(t) - q_{00}|] = \frac{1}{2}.$$

Integrate both sides or functions of t to get

$$\ln |p(t) - q_{00}| = \frac{t}{2} + C$$

and exponentiate to get ~~make sense?~~

$$|p(t) - q_{00}| = e^{\frac{t}{2} + C} = e^{\frac{t}{2}} e^C \text{ make sense?}$$

If we can "solve" this for $p(t)$ we are done
since we would have an expression for
the $p(t)$ that solves ⑥.

Q: Given $|p(t) - q_{00}| = e^{\frac{t}{2}} e^C$, can $p(t) = q_{00}$?

Why or why not?

Re ODE ① has 3 types of solutions:

$$\textcircled{1} \quad p(t) > 900 \text{ always } \Rightarrow p(t) - 900 = K e^{4t}$$

$$\text{or } p(t) = 900 + K e^{4t}, \text{ where } K = e^c > 0.$$

$$\textcircled{2} \quad p(t) < 900 \text{ always } \Rightarrow -(p(t) - 900) = K e^{4t}$$

$$\text{or } p(t) = 900 + \underbrace{(-K)}_{\text{negative constant}} e^{4t}, \text{ where } K = e^c > 0.$$

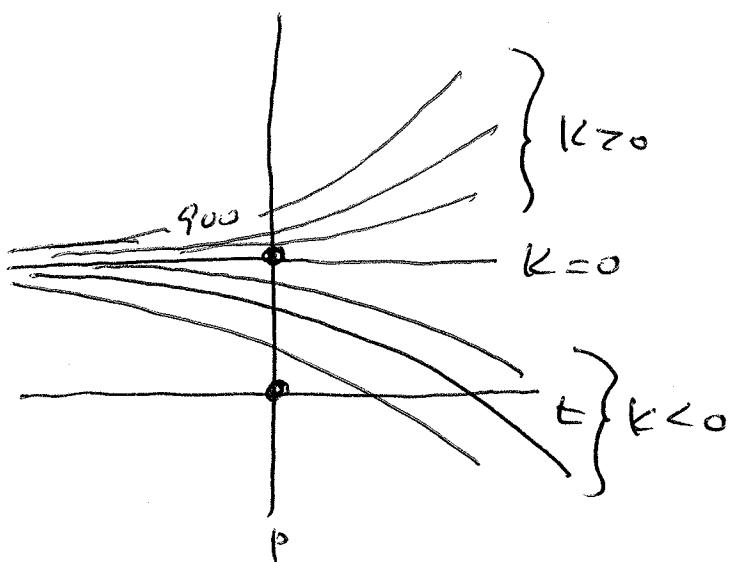
$$\textcircled{3} \quad p(t) = 900 \text{ for all } t \in \mathbb{R}. \text{ It works in the ODE and can also be written}$$

$$p(t) = 900 + K e^{4t}, \quad K = 0.$$

This last solution is called a singular solution which sometimes become hidden due to the method employed to find the other solutions.

Note: Our method included a divide by $p - 900$ term which implied we discounted that possibility. We need to account for it.

Conclusion: $p(t) = 900 + Ke^{kt}$, $k \in \mathbb{R}$
is the general solution to ⑥



Here the singular solution
 $p(t) = 900 \quad \forall t$ is
called an equilibrium
solution (or a steady-
state soln).

Equilibrium solutions will be very important
to us in the future.

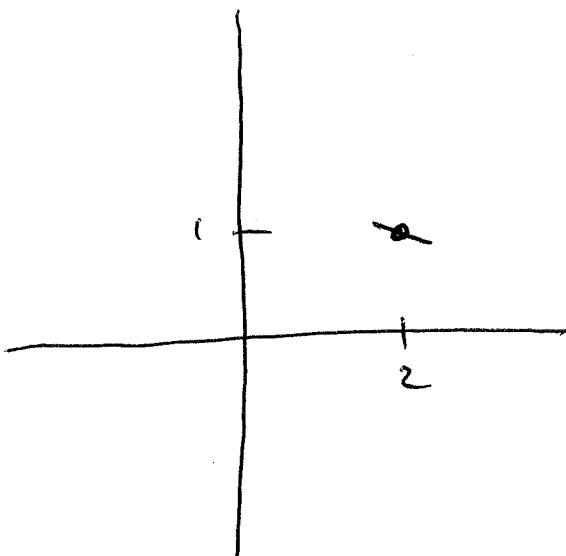
Notice in both ⑥ and ⑦ above

$$\frac{dy}{dx} = \text{something involving } x, y$$

$$\frac{dp}{dt} = \text{something involving } t, p$$

This is useful since solutions "live" in the x, y -plane
or the t, p -plane, any solution curve will have
its tangent line at (x, y) with slope given by
simply evaluating the RHS at that point.

ex. For $y' = x - e^{x^2}$, choose $(x_0, y_0) = (2, 1)$.



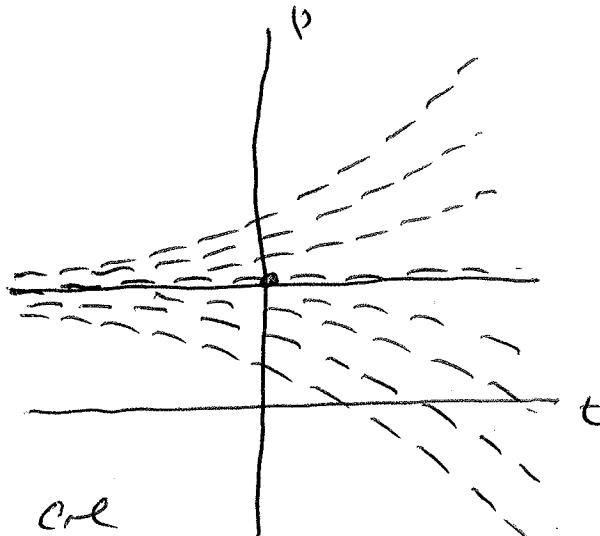
$$\text{Then } \left. \frac{dy}{dx} \right|_{\substack{x=2 \\ y=1}} = 2 - e^{4/2} \approx -0.718$$

The solution curve passing through $(2, 1)$ will have slope ≈ -0.718 there.

Without solving the ODE, we can take a grid of pts in the xy -plane and evaluate these little slope lines. The result is called a slope field:

like blades of grass

in a stream with
a strong current.



These line segments are tangent to all solution curves.

We will use this as a method of study over time.