

Section 9.3

2. Let $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$, $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$, and $\vec{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$.

(a) Show by direct calculation that $A(\vec{x} + \vec{y}) = A\vec{x} + A\vec{y}$.

(b) Show by direct calculation that $A(\lambda\vec{x}) = \lambda(A\vec{x})$.

Answer: (a)

$$\begin{aligned}
 A(\vec{x} + \vec{y}) &= \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \right) = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 + y_1 \\ x_2 + y_2 \end{bmatrix} \\
 &= \begin{bmatrix} a_{11}(x_1 + y_1) + a_{12}(x_2 + y_2) \\ a_{21}(x_1 + y_1) + a_{22}(x_2 + y_2) \end{bmatrix} = \begin{bmatrix} (a_{11}x_1 + a_{12}x_2) + (a_{11}y_1 + a_{12}y_2) \\ (a_{21}x_1 + a_{22}x_2) + (a_{21}y_1 + a_{22}y_2) \end{bmatrix} \\
 &= \begin{bmatrix} a_{11}x_1 + a_{12}x_2 \\ a_{21}x_1 + a_{22}x_2 \end{bmatrix} + \begin{bmatrix} a_{11}y_1 + a_{12}y_2 \\ a_{21}y_1 + a_{22}y_2 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \\
 &= A\vec{x} + A\vec{y}.
 \end{aligned}$$

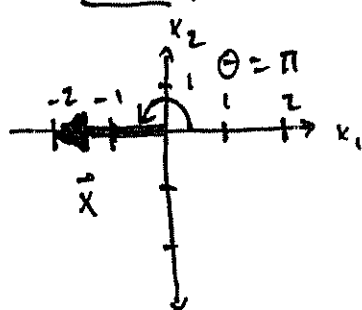
$$\begin{aligned}
 (b) \quad A(\lambda\vec{x}) &= \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \left(\lambda \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \right) = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} \lambda x_1 \\ \lambda x_2 \end{bmatrix} \\
 &= \begin{bmatrix} a_{11}\lambda x_1 + a_{12}\lambda x_2 \\ a_{21}\lambda x_1 + a_{22}\lambda x_2 \end{bmatrix} = \begin{bmatrix} \lambda(a_{11}x_1 + a_{12}x_2) \\ \lambda(a_{21}x_1 + a_{22}x_2) \end{bmatrix} \\
 &= \lambda \begin{bmatrix} a_{11}x_1 + a_{12}x_2 \\ a_{21}x_1 + a_{22}x_2 \end{bmatrix} = \lambda \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \lambda(A\vec{x}).
 \end{aligned}$$

Represent each vector in the x_1, x_2 -plane, and determine its length and the angle it forms with the positive x_1 -axis (measured counterclockwise).

(2)

4. $\vec{x} = \begin{bmatrix} -2 \\ 0 \end{bmatrix}$.

Answer:

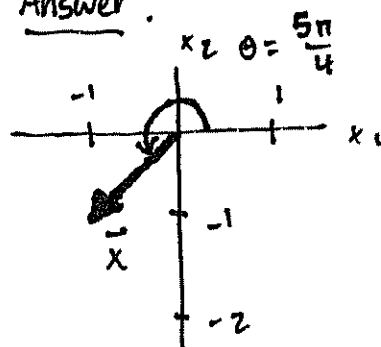


Length: $|\vec{x}| = \sqrt{(-2)^2 + 0^2} = 2$

Angle: $\theta = \pi$ (or 180° , but you should use radians)

6. $\vec{x} = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$.

Answer:



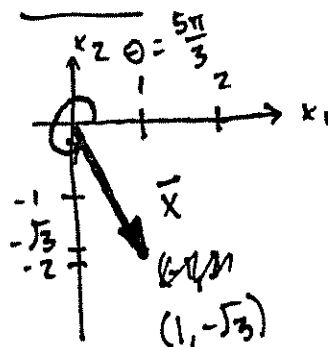
Length: $|\vec{x}| = \sqrt{(-1)^2 + (-1)^2} = \sqrt{2}$

Angle: $\tan \theta = \frac{-1}{-1} = 1$

$\theta = \tan^{-1}(1) + \pi$
 $= \frac{\pi}{4} + \pi = \frac{5\pi}{4}$

8. $\vec{x} = \begin{bmatrix} 1 \\ -\sqrt{3} \end{bmatrix}$.

Answer



Length: $|\vec{x}| = \sqrt{1 + (-\sqrt{3})^2} = 2$

Angle:

~~$\tan \theta = \frac{-\sqrt{3}}{1} = -\sqrt{3}$
 $\theta = \tan^{-1}(-\sqrt{3}) = -\frac{\pi}{3}$
 $\theta = -\frac{\pi}{3} + 2\pi = \frac{11\pi}{6}$~~

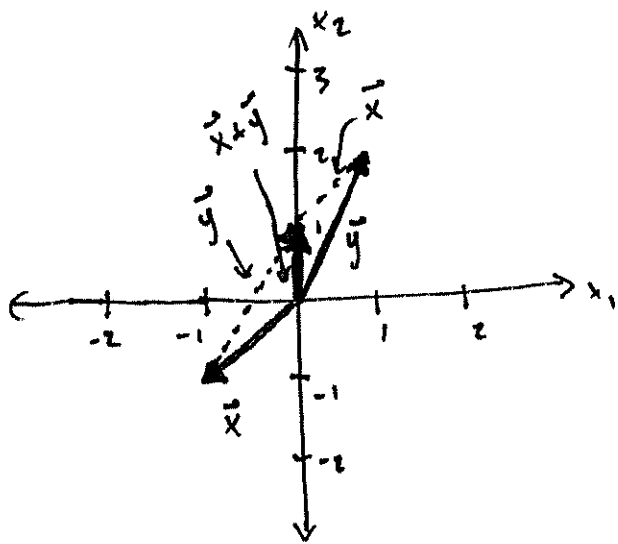
$\tan \theta = -\sqrt{3}$

$\theta = \tan^{-1}(-\sqrt{3}) + 2\pi = -\frac{\pi}{3} + 2\pi = \frac{11\pi}{6}$

20. Find $\vec{x} + \vec{y}$, and graph $\vec{x}$, $\vec{y}$, and $\vec{x} + \vec{y}$.

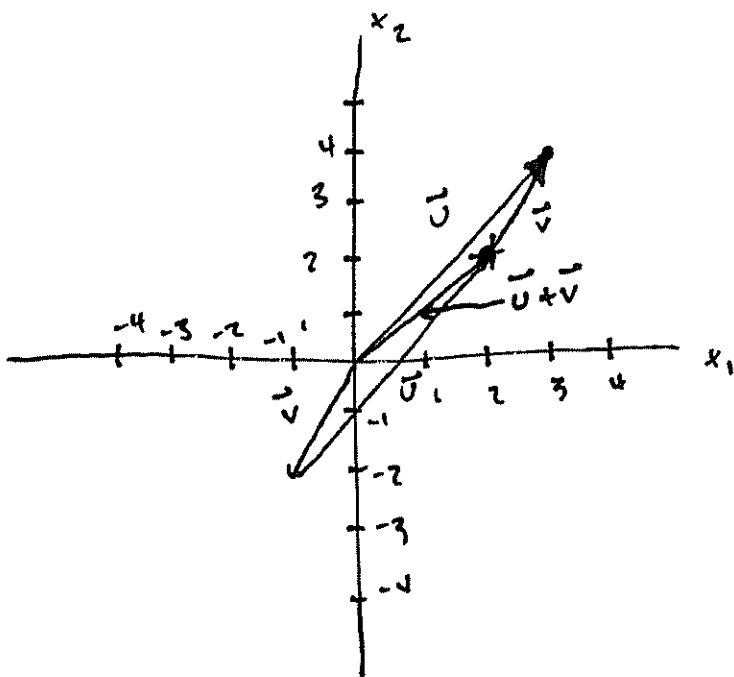
(3)

Answer: $\vec{x} = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$, $\vec{y} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$, so $\vec{x} + \vec{y} = \begin{bmatrix} -1 \\ -1 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -1+1 \\ -1+2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$.



29. Let $\vec{u} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} -1 \\ -2 \end{bmatrix}$. Compute $\vec{u} + \vec{v}$ and illustrate the result graphically.

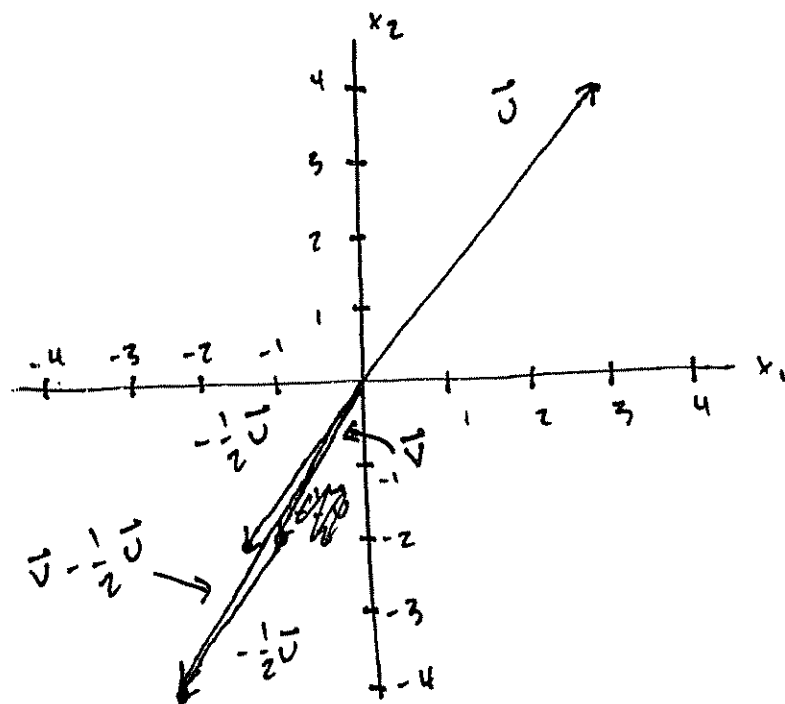
Answer: $\vec{u} + \vec{v} = \begin{bmatrix} 3 \\ 4 \end{bmatrix} + \begin{bmatrix} -1 \\ -2 \end{bmatrix} = \begin{bmatrix} 3-1 \\ 4-2 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$.



32. Compute $\vec{v} - \frac{1}{2}\vec{u}$ and illustrate the result graphically.

(4)

Answer: $\vec{v} - \frac{1}{2}\vec{u} = \begin{bmatrix} -1 \\ -2 \end{bmatrix} - \begin{bmatrix} 3/2 \\ 2 \end{bmatrix} = \begin{bmatrix} -5/2 \\ -4 \end{bmatrix}$



If your graphs don't look that great, well, mine don't either.

The book chose vectors that are nearly parallel, which makes the parallelogram you draw quite thin.

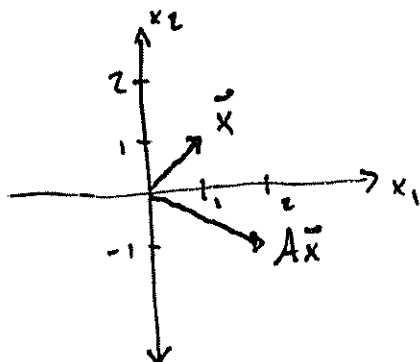
36. Give a geometric interpretation of the map $\vec{x} \rightarrow A\vec{x}$ for

$$A = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix}.$$

Answer: If $\vec{x} = \begin{bmatrix} a \\ b \end{bmatrix}$, $A\vec{x} = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 2a \\ -b \end{bmatrix}$.

So A doubles the x_1 coordinate and negates the x_2 coordinate.

For example: if $\vec{x} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $A\vec{x} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$, which looks like this:



(5)

54. Let $A = \begin{bmatrix} 3 & 6 \\ -1 & -4 \end{bmatrix}$. Find the eigenvalues and eigenvectors for A .

Determine the equations for the lines through the origin in the direction of the eigenvectors, and graph the lines along with the eigenvectors and A times the eigenvectors.

Answer: First find the eigenvalues: solve the system

$$\det(A - \lambda I_2) = 0$$

$$0 = \begin{vmatrix} 3-\lambda & 6 \\ -1 & -4-\lambda \end{vmatrix} = (3-\lambda)(-4-\lambda) - (-1)(6)$$

$$= -12 - 3\lambda + 4\lambda + \lambda^2 + 6$$

$$= \lambda^2 + \lambda - 6 = (\lambda + 3)(\lambda - 2)$$

So eigenvalues are $\lambda_1 = -3$ and $\lambda_2 = 2$.

Now find the eigenvectors:

Eigenvector for $\lambda_1 = -3$

$$\begin{bmatrix} 3 - (-3) & 6 \\ -1 & -4 - (-3) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 6 & 6 & : & 0 \\ -1 & -1 & : & 0 \end{bmatrix} \xrightarrow{6R_2 + R_1 \rightarrow R_1} \begin{bmatrix} 0 & 0 & : & 0 \\ -1 & -1 & : & 0 \end{bmatrix}$$

$$\xrightarrow{-R_2 \rightarrow R_2} \begin{bmatrix} 0 & 0 & : & 0 \\ 1 & 1 & : & 0 \end{bmatrix}. \text{ We get the equation } x_1 + x_2 = 0, \text{ or } x_2 = -x_1.$$

So any vector of the form $\begin{bmatrix} x_1 \\ -x_1 \end{bmatrix}$ is an eigenvector with eigenvalue

$\lambda_1 = -3$. Choose $x_1 = 1$, and let $v_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ be our eigenvector.

Eigenvector for $\lambda_2 = 2$:

(6)

$$\begin{bmatrix} 3-2 & 6 & : & 0 \\ -1 & -4-2 & : & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 6 & : & 0 \\ -1 & -6 & : & 0 \end{bmatrix} \xrightarrow{R_1 + 2R_2 \rightarrow R_2} \begin{bmatrix} 1 & 6 & : & 0 \\ 0 & 0 & : & 0 \end{bmatrix}$$

We get the equation $x_1 + 6x_2 = 0$, or $x_2 = -\frac{1}{6}x_1$. Choose $x_1 = 6$;

then $u_2 = \begin{bmatrix} 6 \\ -1 \end{bmatrix}$.

Now for the graph: Since A times an eigenvector equals the eigenvector times its eigenvalue,

$$Au_1 = \lambda_1 u_1 = -3u_1 = \begin{bmatrix} -3 \\ 3 \end{bmatrix}$$

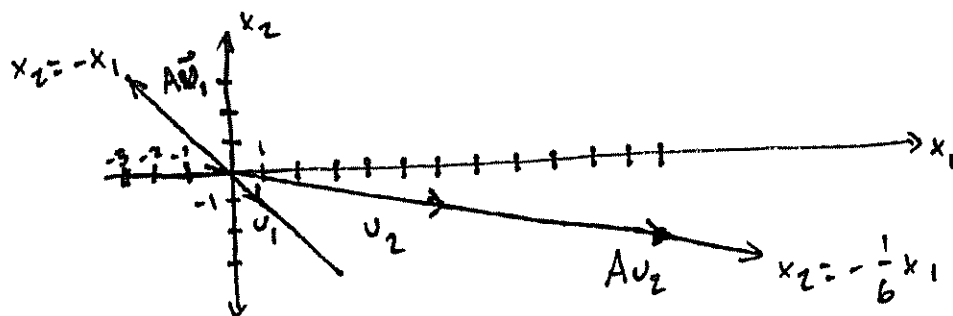
$$Au_2 = \lambda_2 u_2 = 2u_2 = \begin{bmatrix} 12 \\ -2 \end{bmatrix}$$

The lines are simply the equations you got when you solved for the eigenvectors:

$$u_1: x_2 = -x_1$$

$$u_2: x_2 = -\frac{1}{6}x_1$$

And here's the graph:



62. Find the eigenvalues for $A = \begin{bmatrix} a & c \\ 0 & b \end{bmatrix}$.

Answers: Eigenvalues occur when $\det(A - \lambda I_2) = 0$:

$$0 = \begin{vmatrix} a-\lambda & c \\ 0 & b-\lambda \end{vmatrix} = (a-\lambda)(b-\lambda).$$

So $\lambda_1 = a$ and $\lambda_2 = b$.

66. Let $A = \begin{bmatrix} 0 & 1 \\ 2 & -1 \end{bmatrix}$. Without explicitly computing the eigenvalues of A , decide whether the real parts of both eigenvalues are positive or negative.

Answer: Use the theorem on p. 480:

THEOREM Let A be a 2×2 matrix with eigenvalues λ_1 and λ_2 .

Then the real parts of λ_1 and λ_2 are negative if and only if

$$\operatorname{tr} A < 0 \quad \text{and} \quad \det A > 0.$$

$$\text{Since } \det A = \begin{vmatrix} 0 & 1 \\ 2 & -1 \end{vmatrix} = (0)(-1) - (1)(2) = -2$$

and $\operatorname{tr} A = 0 + (-1) = -1$, the real parts of λ_1 and λ_2 are not both negative.

70. Let $A = \begin{bmatrix} -2 & 1 \\ -4 & 3 \end{bmatrix}$.

(a) Show that

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 4 \end{bmatrix} \quad \text{and} \quad \vec{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

are eigenvectors of A and are linearly independent.

(b) Represent

$$\vec{x} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

as a linear combination of $\vec{v}_1$ and $\vec{v}_2$.

Answer:

$$A \vec{v}_1 = \begin{bmatrix} -2 & 1 \\ -4 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \end{bmatrix} = \begin{bmatrix} -2 + 4 \\ -4 + 12 \end{bmatrix} = \begin{bmatrix} 2 \\ 8 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

So $A \vec{v}_1 = 2 \vec{v}_1$, which means $\vec{v}_1$ is an eigenvector of A with eigenvalue 2.

$$A \vec{v}_2 = \begin{bmatrix} -2 & 1 \\ -4 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -2 + 1 \\ -4 + 3 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \end{bmatrix} = (-1) \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

So $A \vec{v}_2 = -\vec{v}_2$, which means $\vec{v}_2$ is an eigenvector of A with eigenvalue -1. The eigenvectors $\vec{v}_1$ and $\vec{v}_2$ are linearly independent if $a_1 \vec{v}_1 + a_2 \vec{v}_2 = \vec{0}$ if and only if $a_1 = a_2 = 0$. So solve for a_1 and a_2 :

$$a_1 \begin{bmatrix} 1 \\ 4 \end{bmatrix} + a_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

We know that $a_1 = a_2 = 0$ if and only if $\begin{vmatrix} 1 & 1 \\ 4 & 1 \end{vmatrix} \neq 0$ by the theorem on p. 455. Since $\begin{vmatrix} 1 & 1 \\ 4 & 1 \end{vmatrix} = 1 - 4 = -3 \neq 0$, $a_1 = a_2 = 0$, which means $\vec{v}_1$ and $\vec{v}_2$ are linearly independent.

(9)

(b) We want a_1 and a_2 such that

$$\vec{x} = a_1 \vec{v}_1 + a_2 \vec{v}_2; \quad \text{in other words}$$

$$\begin{bmatrix} 1 & 1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & -1 \\ 4 & 1 & 2 \end{bmatrix}$$

$$\xrightarrow{-4R_1 + R_2 \rightarrow R_2} \begin{bmatrix} 1 & 1 & -1 \\ 0 & -3 & 6 \end{bmatrix} \xrightarrow{-\frac{1}{3}R_2 \rightarrow R_2} \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & -2 \end{bmatrix}$$

$$\xrightarrow{-R_2 + R_1 \rightarrow R_1} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \end{bmatrix}. \quad \text{So } a_1 = 1 \text{ and } a_2 = -2,$$

which means $\vec{x} = \vec{v}_1 - 2\vec{v}_2$, or

$$\begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix} - 2 \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

(c) Use your results in (a) and (b) to compute $A^{10} \vec{x}$.

Answer:

$$\begin{aligned} A^{10} \vec{x} &= A^{10}(\vec{v}_1 - 2\vec{v}_2) = A^{10} \vec{v}_1 - 2A^{10} \vec{v}_2 \\ &= z^{10} \vec{v}_1 - 2(-1)^{10} \vec{v}_2 \\ &= \begin{bmatrix} z^{10} \\ z^{12} \end{bmatrix} - \begin{bmatrix} 2 \\ 2 \end{bmatrix} = \begin{bmatrix} z(2^9 - 1) \\ z(2^{11} - 1) \end{bmatrix}. \end{aligned}$$